

Enhancing Gravitational Wave Science with Differentiable Models and New Physics Searches

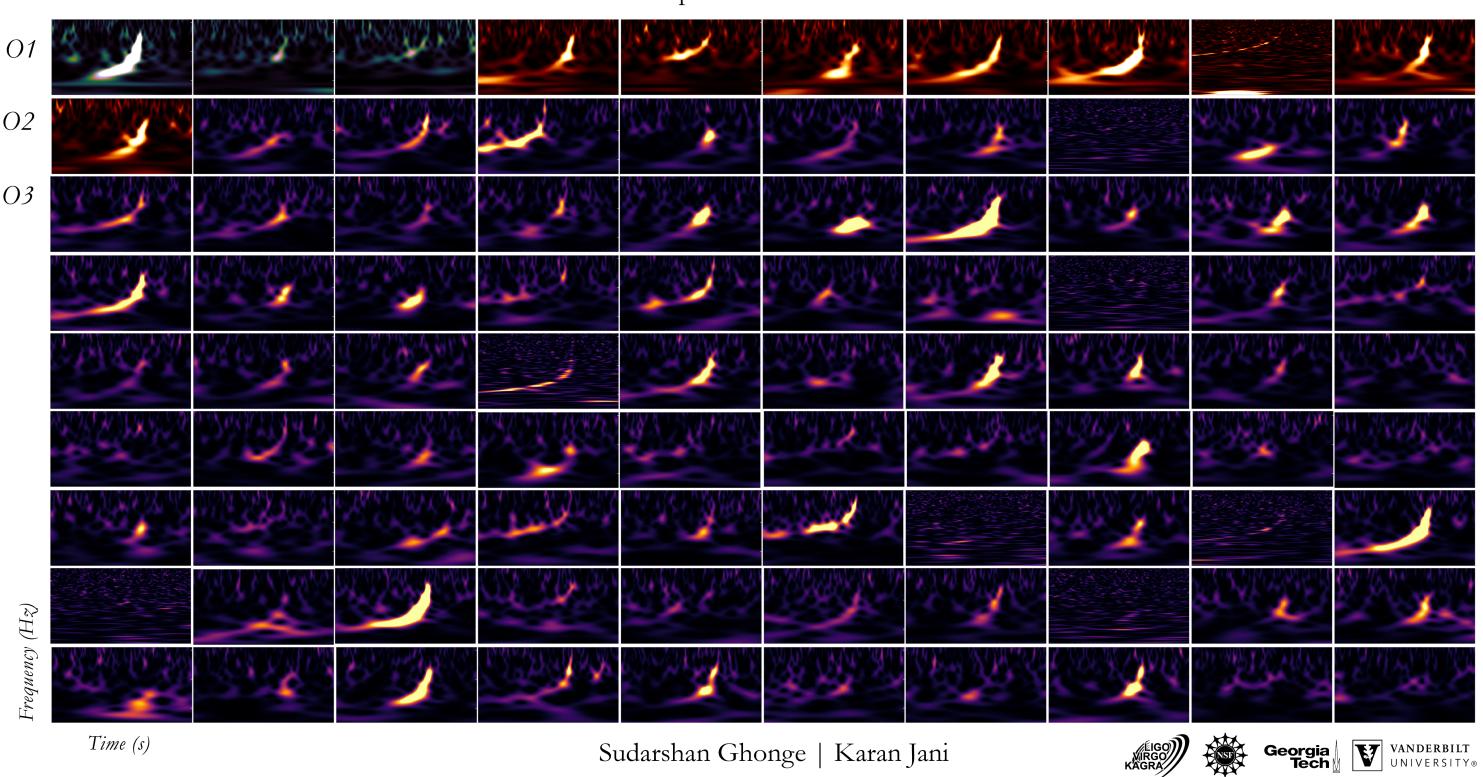
Thomas Edwards | King College London | 16th June 2023

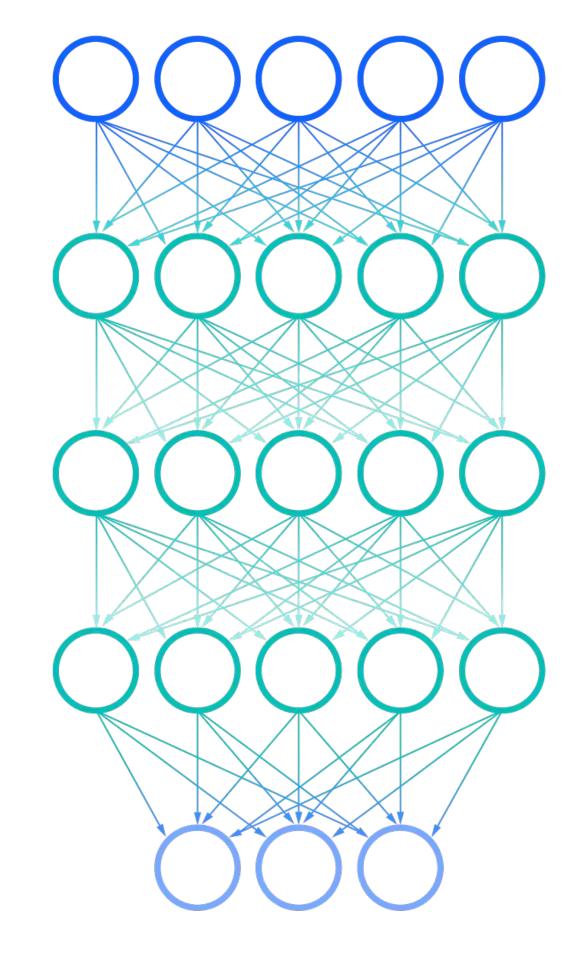


Gravitational Wave + ML Revolution

Gravitational-Wave Transient Catalog

Detections from 2015-2020 of compact binaries with black holes & neutron stars

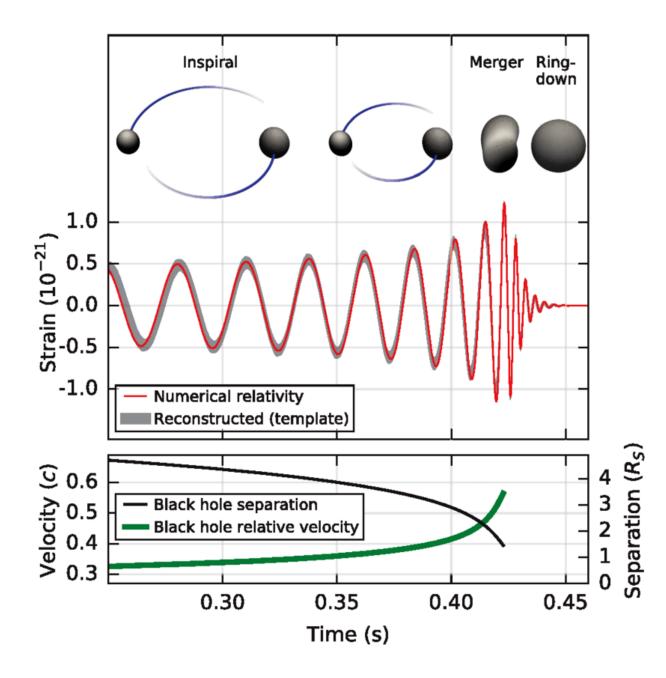








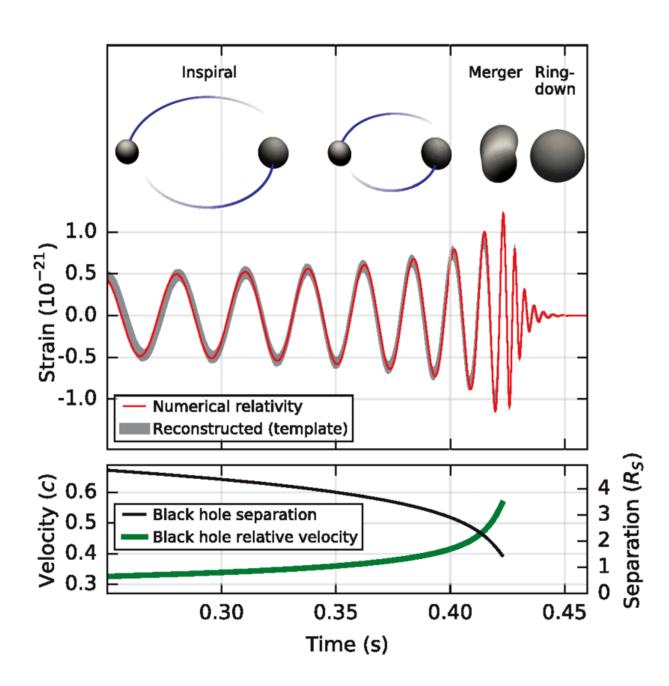


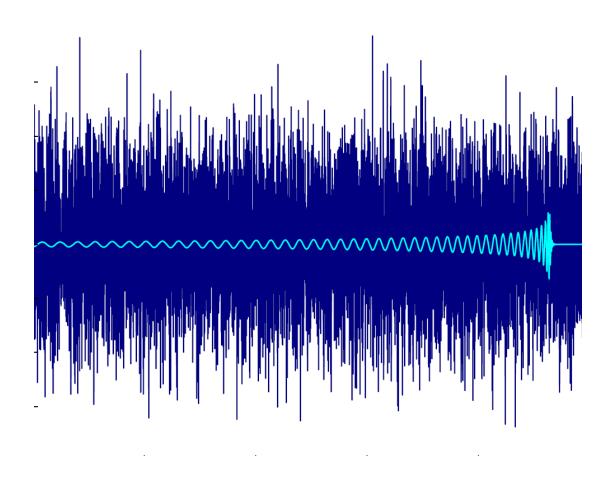






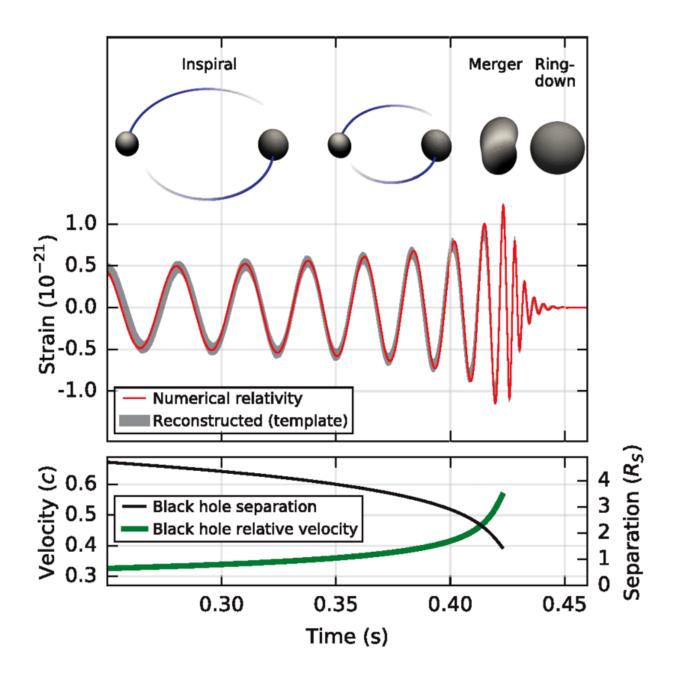


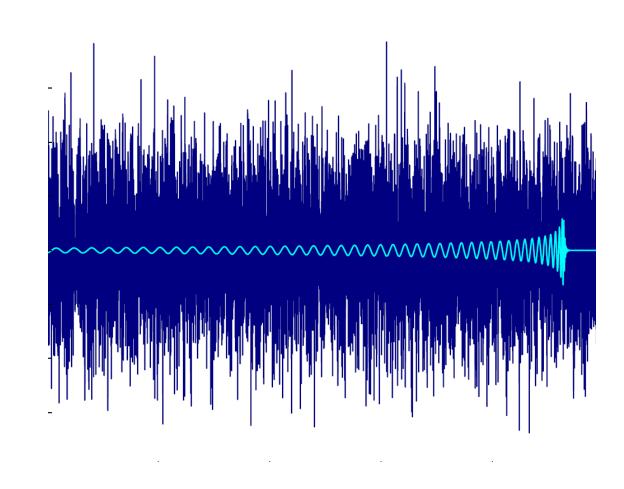


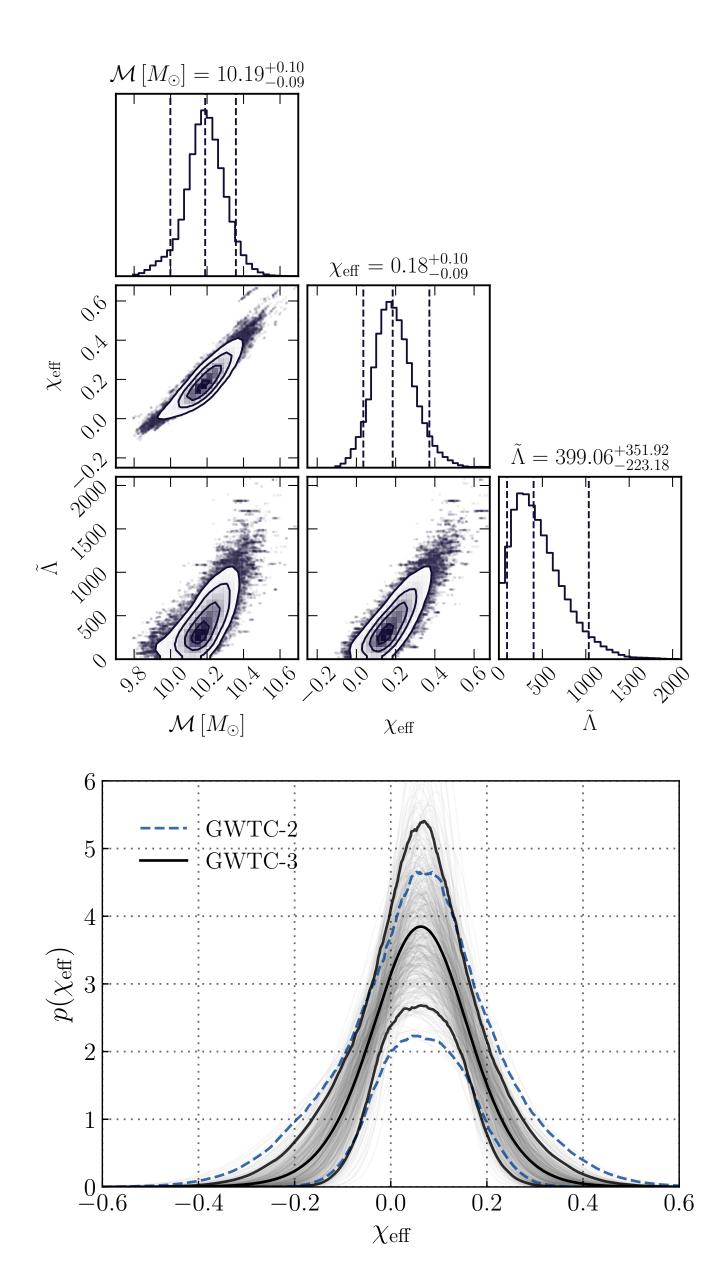






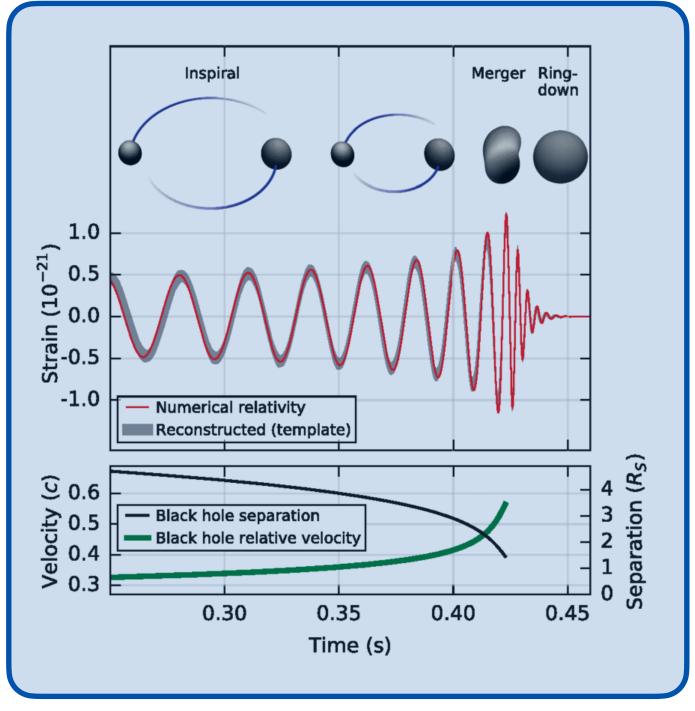


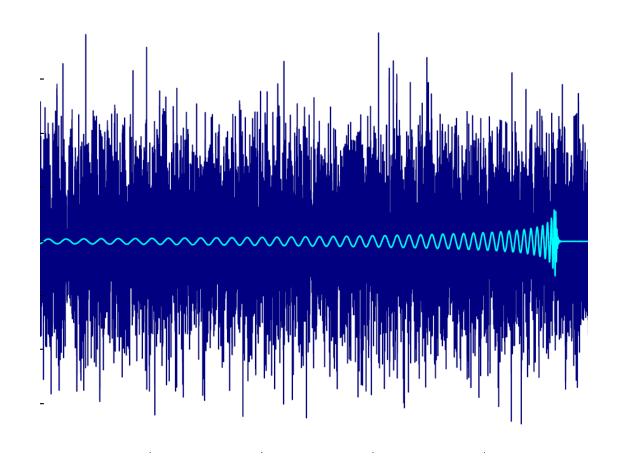


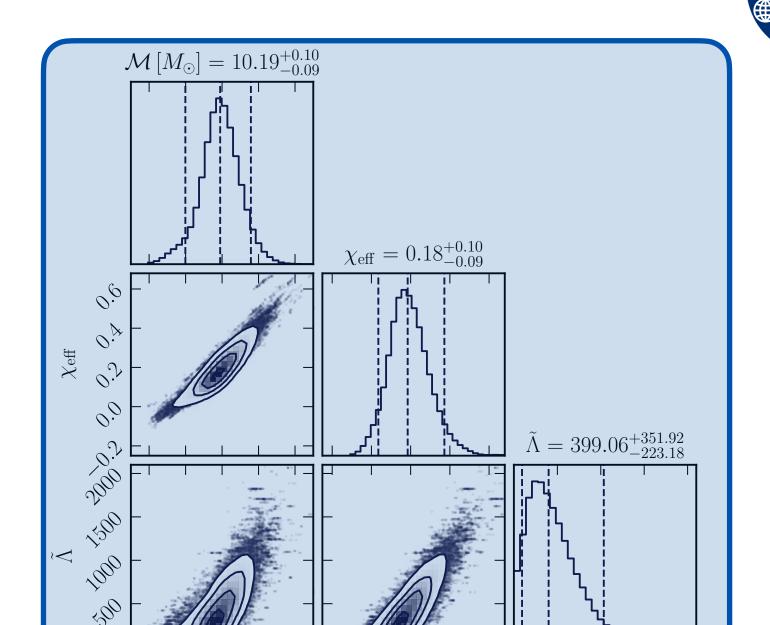


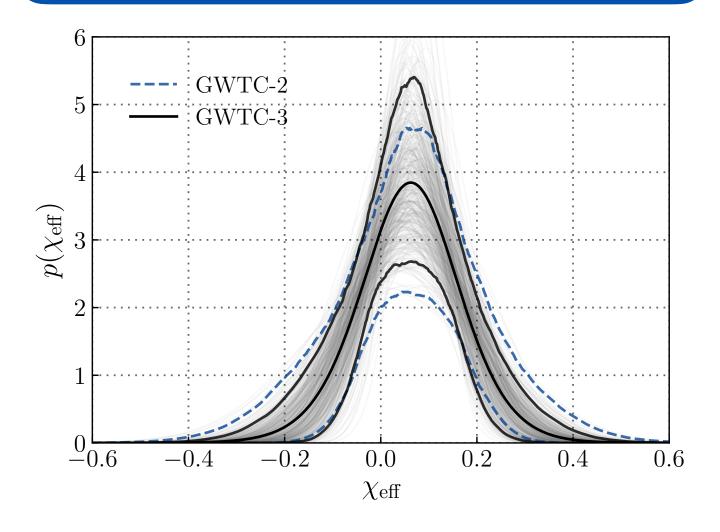
Gravitational Wave Analysis





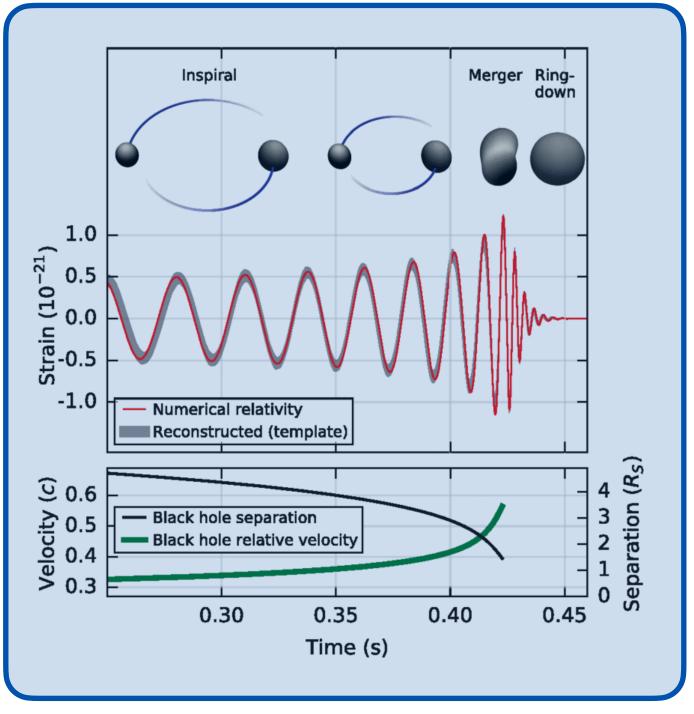


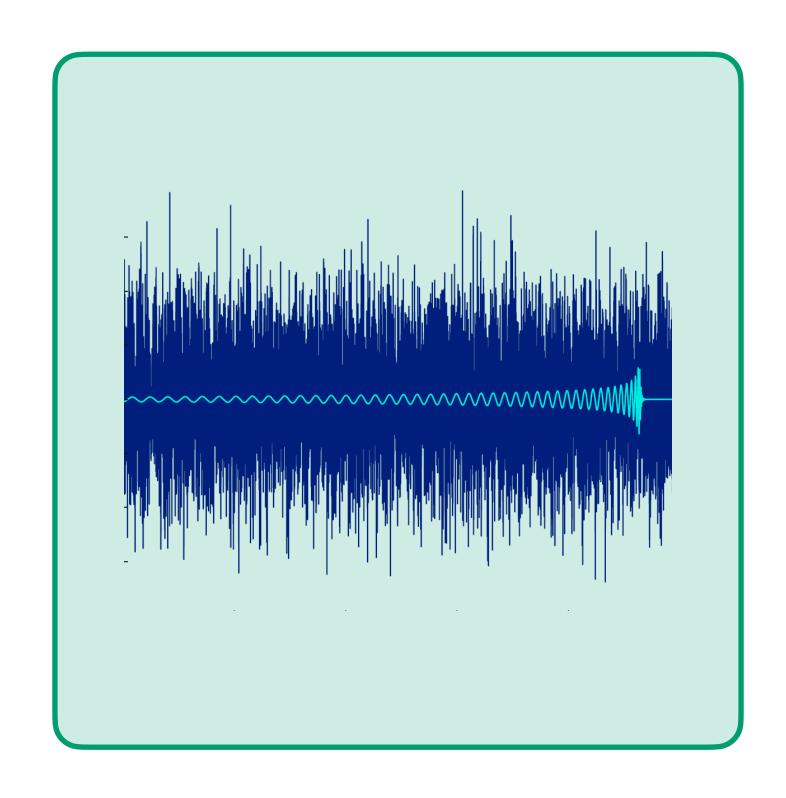


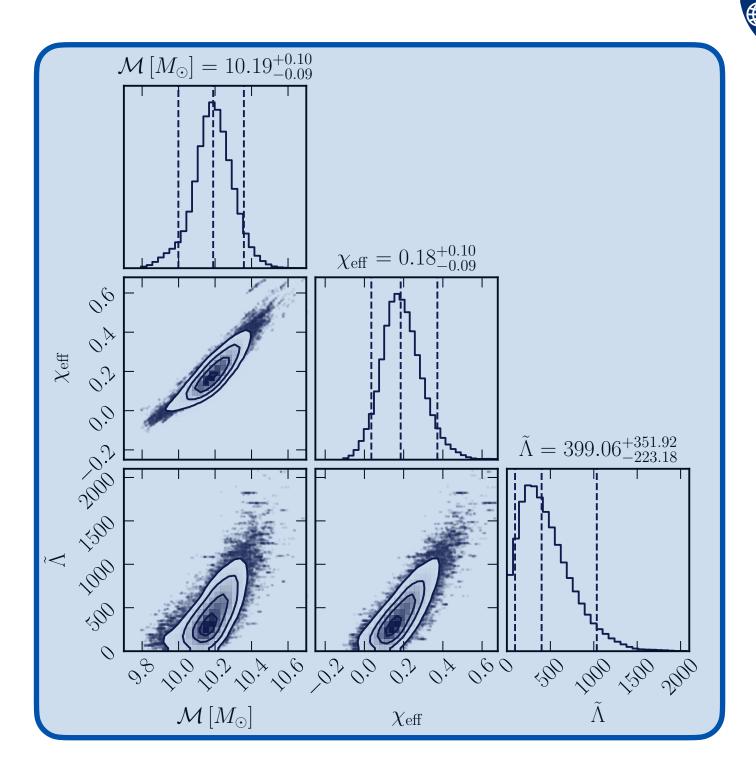


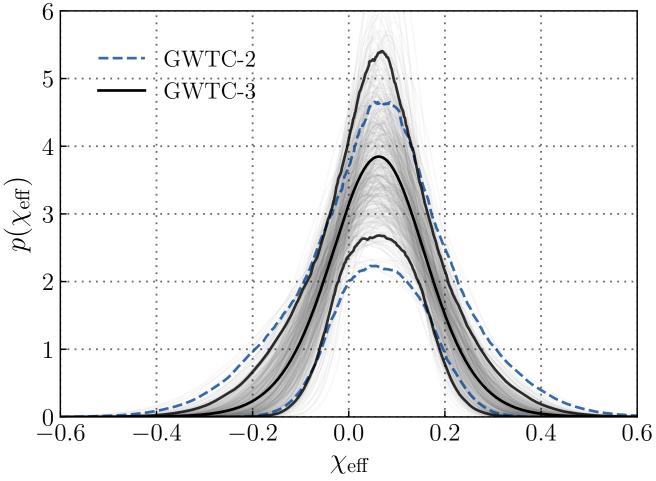
Gravitational Wave Analysis











Overview



How can automaticallydifferentiable models improve GW analysis tasks?



Kaze Wong



Max Isi

+ Kelvin K. H. Lam, Adam Coogan, James Alvey, and Daniel Foreman-Mackey

What could current searches be missing?



Horng Sheng Chia



Jay Wadekar



Aaron Zimmerman

Overview



How can automaticallydifferentiable models improve GW analysis tasks?

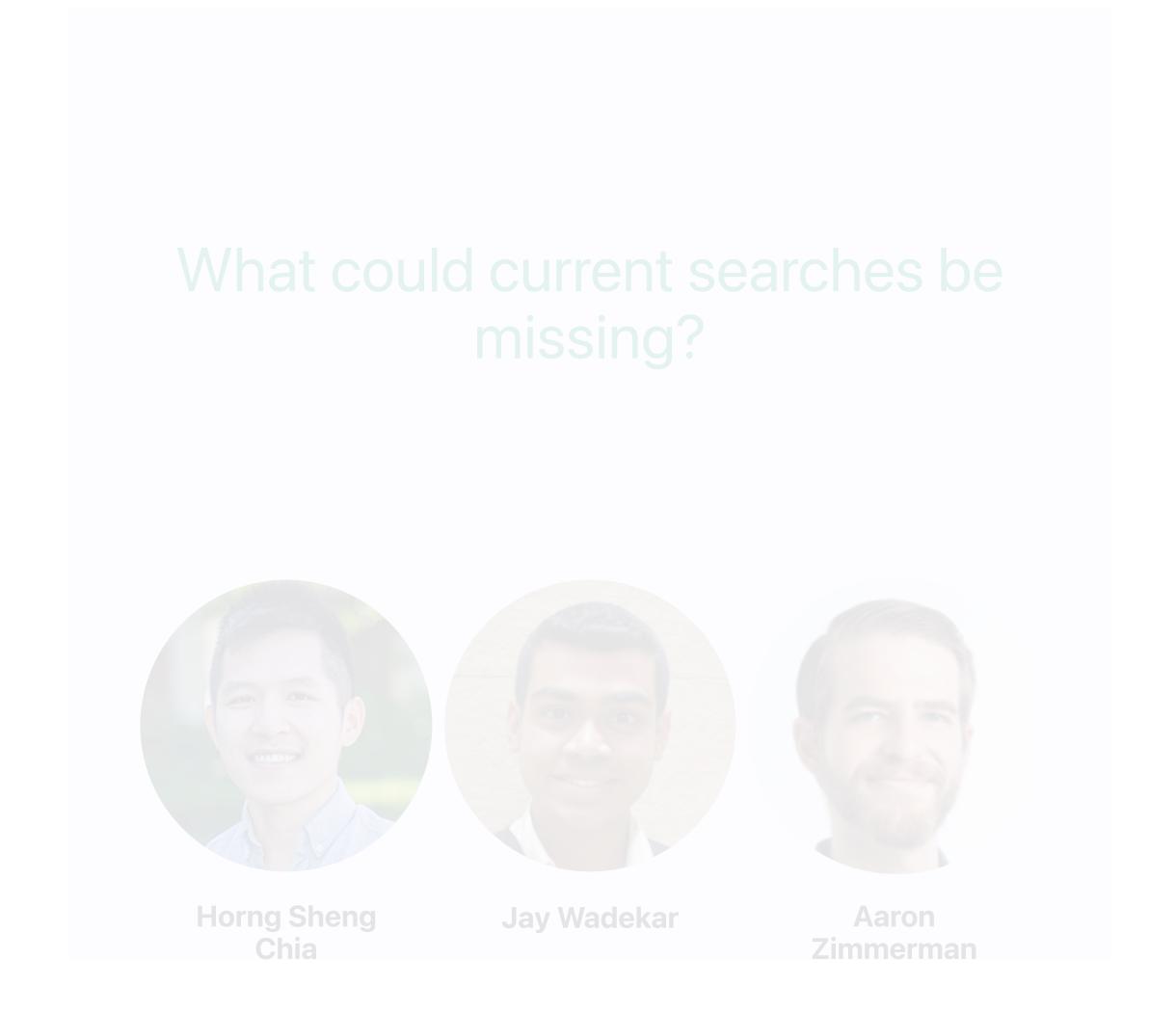


Kaze Wong



Max Isi

+ Kelvin K. H. Lam, Adam Coogan, James Alvey, and Daniel Foreman-Mackey

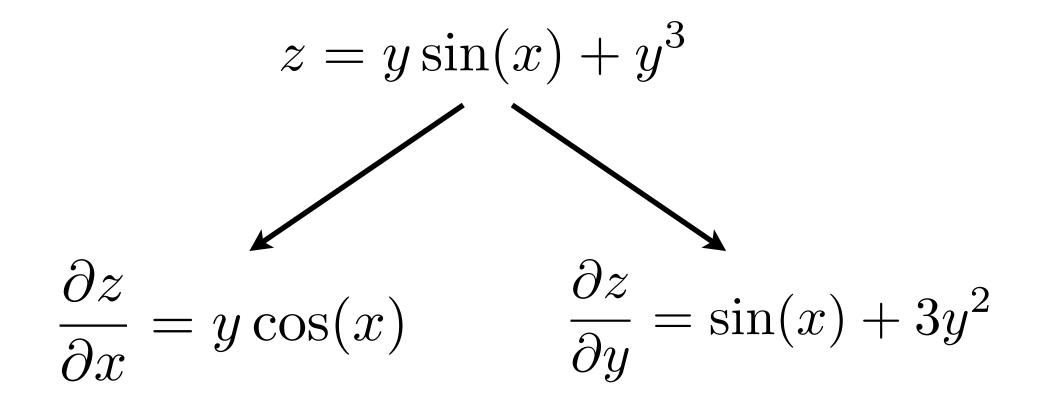




Symbolic and numerical differentiation



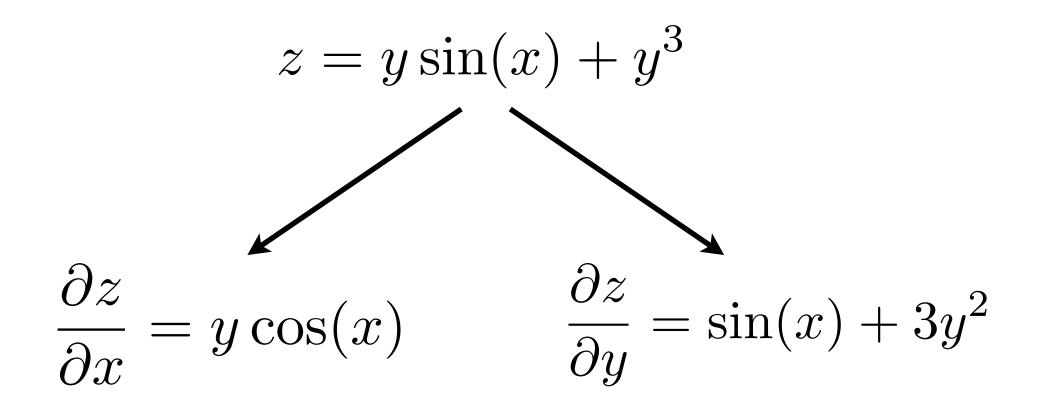
Symbolic and numerical differentiation



- Requires closed-form expressions
- Can lead to "expression swell"



Symbolic and numerical differentiation



- Requires closed-form expressions
- Can lead to "expression swell"

$$f'(x) = \lim_{h \to 0} \frac{f(x+h) - f(x)}{h}$$

- Requires O(n) calls of the function where n is the number of parameters of the function
- Leads to numerical inaccuracies (rounding and truncation error)



What is Automatic Differentiation (AD)?

- Automatic differentiation is a family of methods which allows one to compute machine precision derivatives with little computational overhead for arbitrary computational programs
- Its foundation is that each mathematical step is itself differentiable and composable using the chain rule

$$\frac{\partial w}{\partial t} = \sum_{i}^{N} \frac{\partial w}{\partial u_{i}} \frac{\partial u_{i}}{\partial t}$$

Forward mode AD



- Forward mode breaks down a function into intermediate steps and simultaneously evaluates both the value of the intermediate variable and its derivative (also known as using dual numbers)
- Discussed extensively <u>here</u>
- Runs in \sim n x O(f)

$$f(x_1, x_2) = \sin(x_1 x_2) + x_1 x_2$$





- Forward mode breaks down a function into intermediate steps and simultaneously evaluates both the value of the intermediate variable and its derivative (also known as using dual numbers)
- Discussed extensively <u>here</u>
- Runs in \sim n x O(f)

$$f(x_1, x_2) = \sin(x_1 x_2) + x_1 x_2$$

$$x_1 = ?$$
 $x_2 = ?$
 $a = x_1 x_2$
 $b = \sin(a)$
 $c = a + b$

Forward mode AD



- Forward mode breaks down a function into intermediate steps and simultaneously evaluates both the value of the intermediate variable and its derivative (also known as using dual numbers)
- Discussed extensively <u>here</u>
- Runs in \sim n x O(f)

$$f(x_1, x_2) = \sin(x_1 x_2) + x_1 x_2$$

$$x_1 = ?$$
 $x_2 = ?$
 $dx_1 = 1$
 $dx_2 = 0$
 $a = x_1x_2$
 $da = x_1dx_2 + x_2dx_1$
 $da = cos(a)da$
 $da = a + b$
 $da = cos(a)da$

Forward mode AD



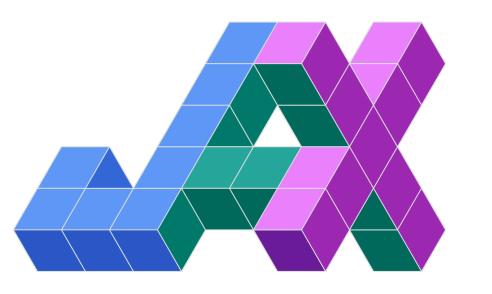
- Forward mode breaks down a function into intermediate steps and simultaneously evaluates both the value of the intermediate variable and its derivative (also known as using dual numbers)
- Discussed extensively <u>here</u>
- Runs in \sim n x O(f)

$$x_1 = ?$$
 $dx_1 = 1$ $dx_2 = 0$ $dx_1 = 1$ $dx_2 = 0$ $dx_1 = 0$ $dx_2 = 0$ $dx_2 = 0$ $dx_1 = 0$ $dx_2 = 0$ $dx_2 = 0$ $dx_1 = 0$ $dx_2 = 0$ $dx_2 = 0$ $dx_1 = 0$ $dx_2 = 0$ $dx_2 = 0$ $dx_1 = 0$ $dx_2 = 0$ $dx_2 = 0$ $dx_1 = 0$ $dx_2 = 0$ $dx_2 = 0$ $dx_1 = 0$ $dx_2 = 0$ $dx_2 = 0$ $dx_2 = 0$ $dx_1 = 0$ $dx_2 = 0$ $dx_3 = 0$

$$f: \mathbb{R}^n \to \mathbb{R}^m$$
, where $n \ll m$

Why JAX?





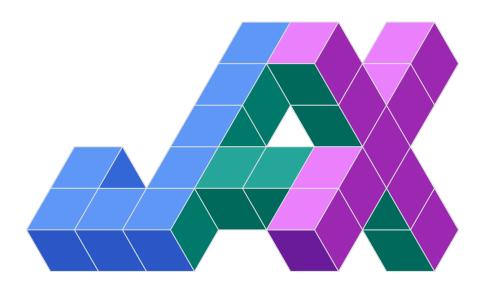
[https://github.com/google/jax]





Runs on pure Python and numpy(ish) code





[https://github.com/google/jax]

Why JAX?

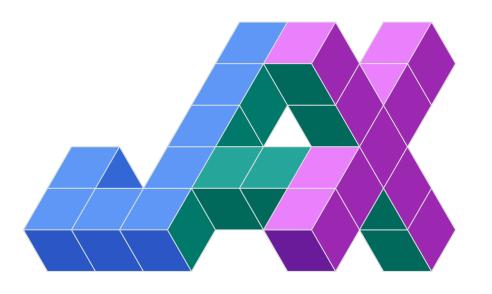


Runs on pure Python and numpy(ish) code



Use XLA compilation to speed up code substantially





[https://github.com/google/jax]

Why JAX?

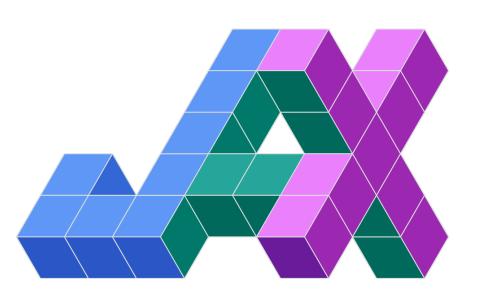


Runs on pure Python and numpy(ish) code



Use XLA compilation to speed up code substantially





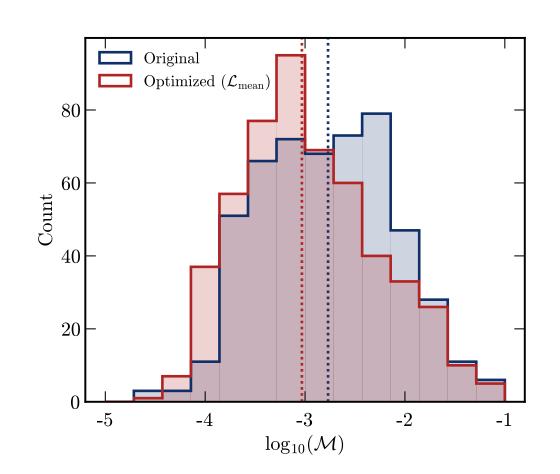
[https://github.com/google/jax]

Scales to different computing architectures and multiple cores or a cluster

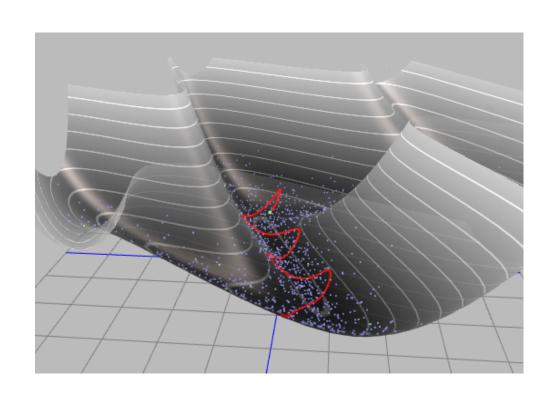


Ripple

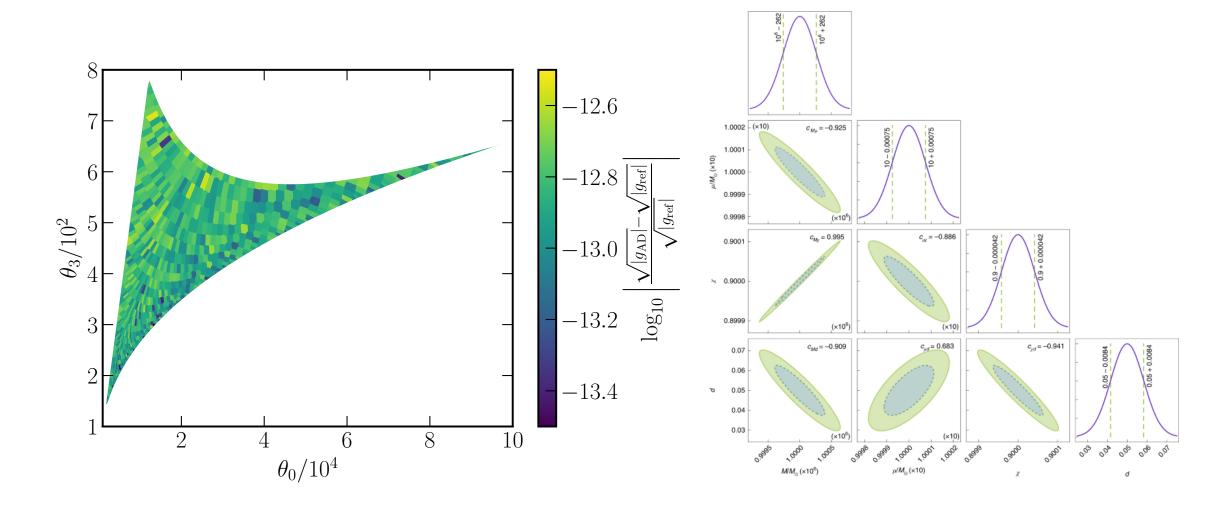




Waveform Optimization



Gradient-based Parameter Estimation

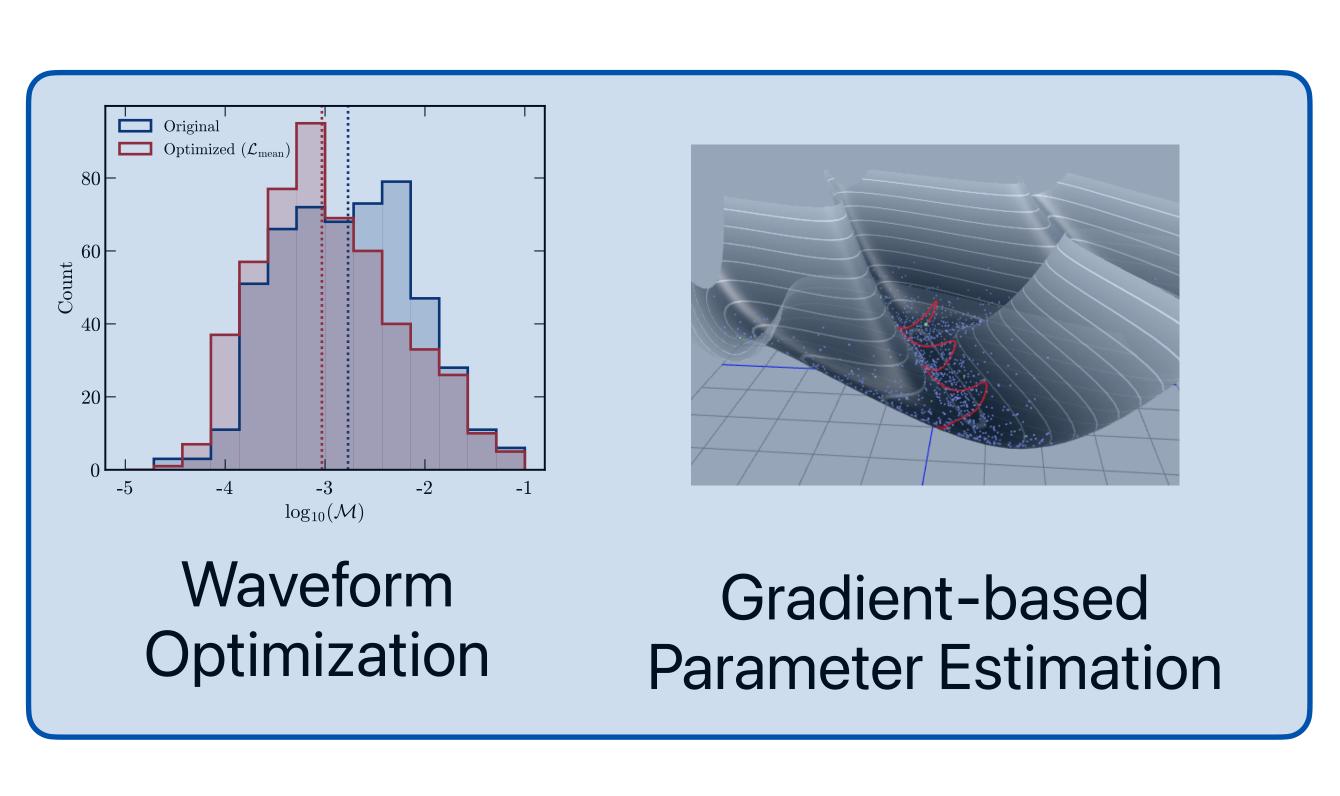


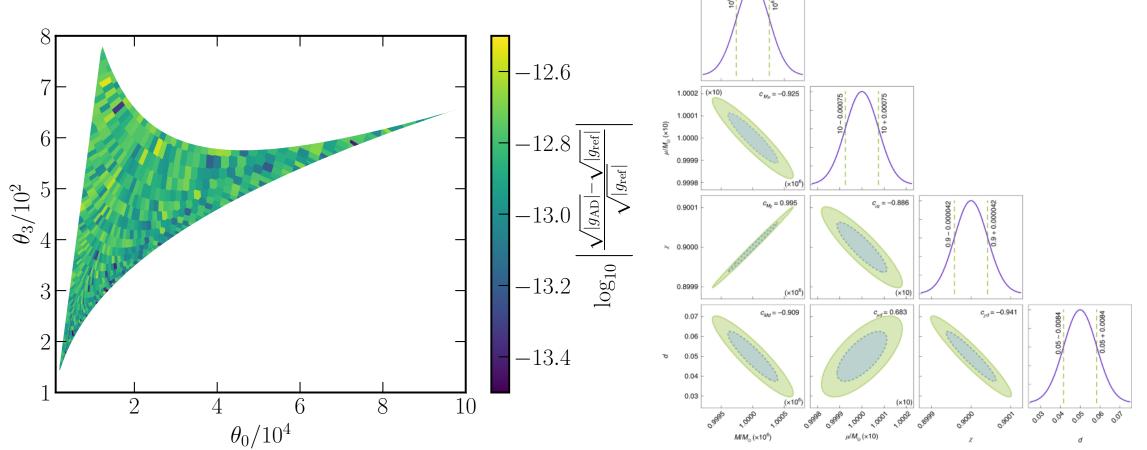
Template Bank Generation

Fisher Analyses

Ripple







Template Bank Generation

Fisher Analyses

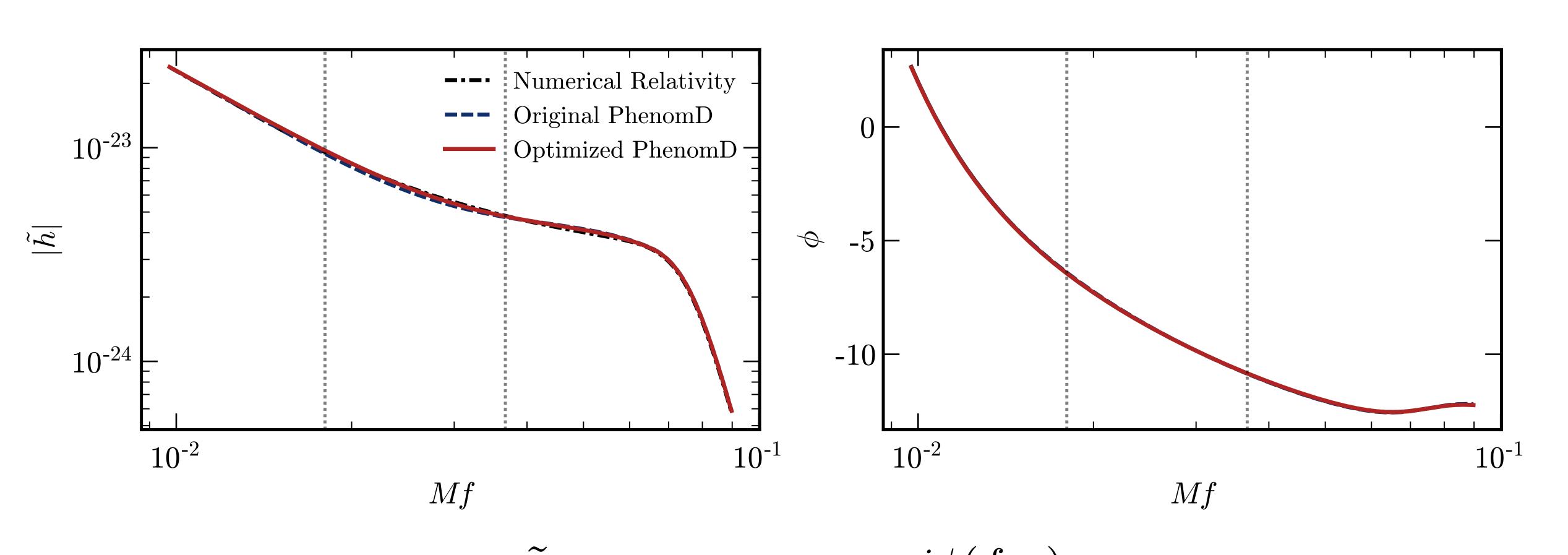




$$\tilde{h}(f; \boldsymbol{p}) = \mathcal{A}(\boldsymbol{p})e^{i\phi(f; \boldsymbol{p})}$$



Optimizing Waveforms

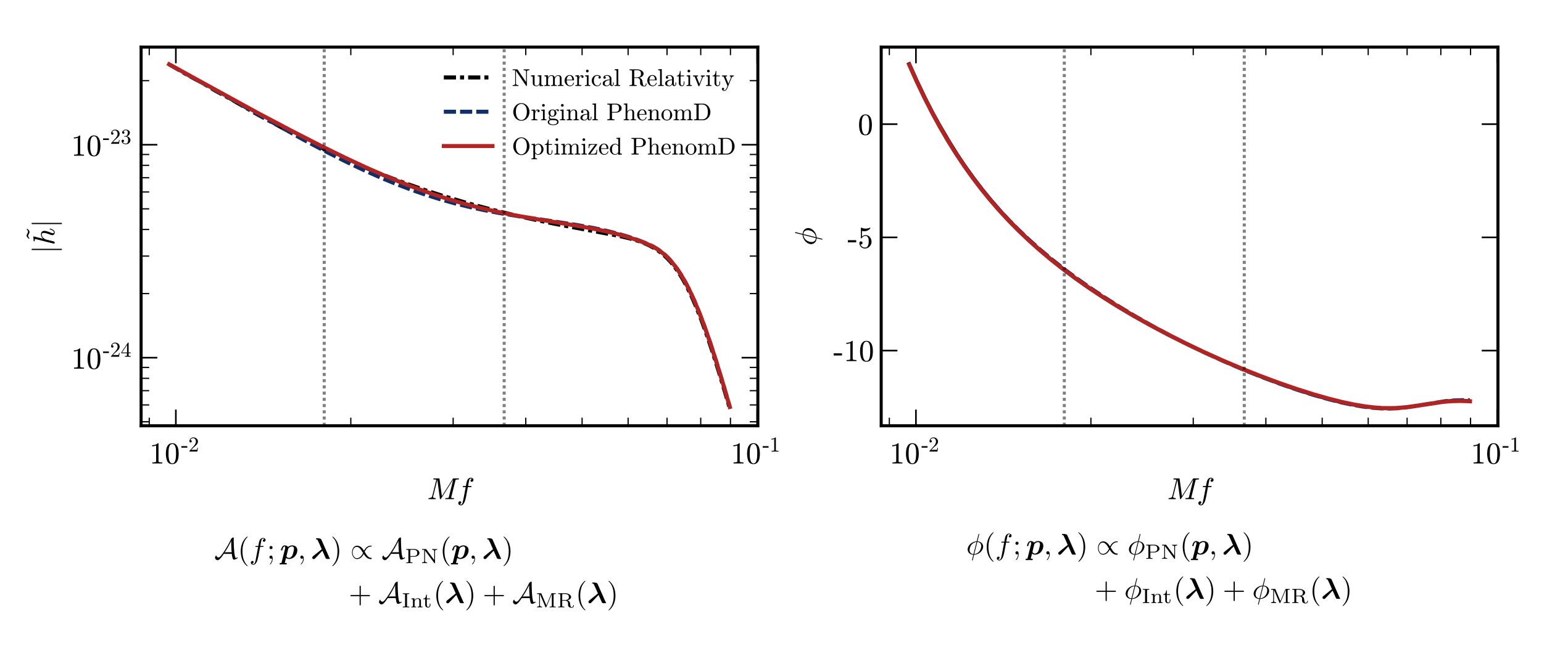


$$\tilde{h}(f; \boldsymbol{p}) = \mathcal{A}(\boldsymbol{p})e^{i\phi(f; \boldsymbol{p})}$$





Optimizing Waveforms





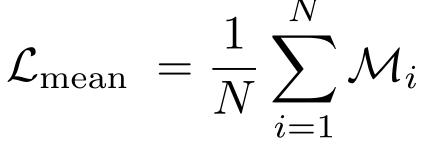


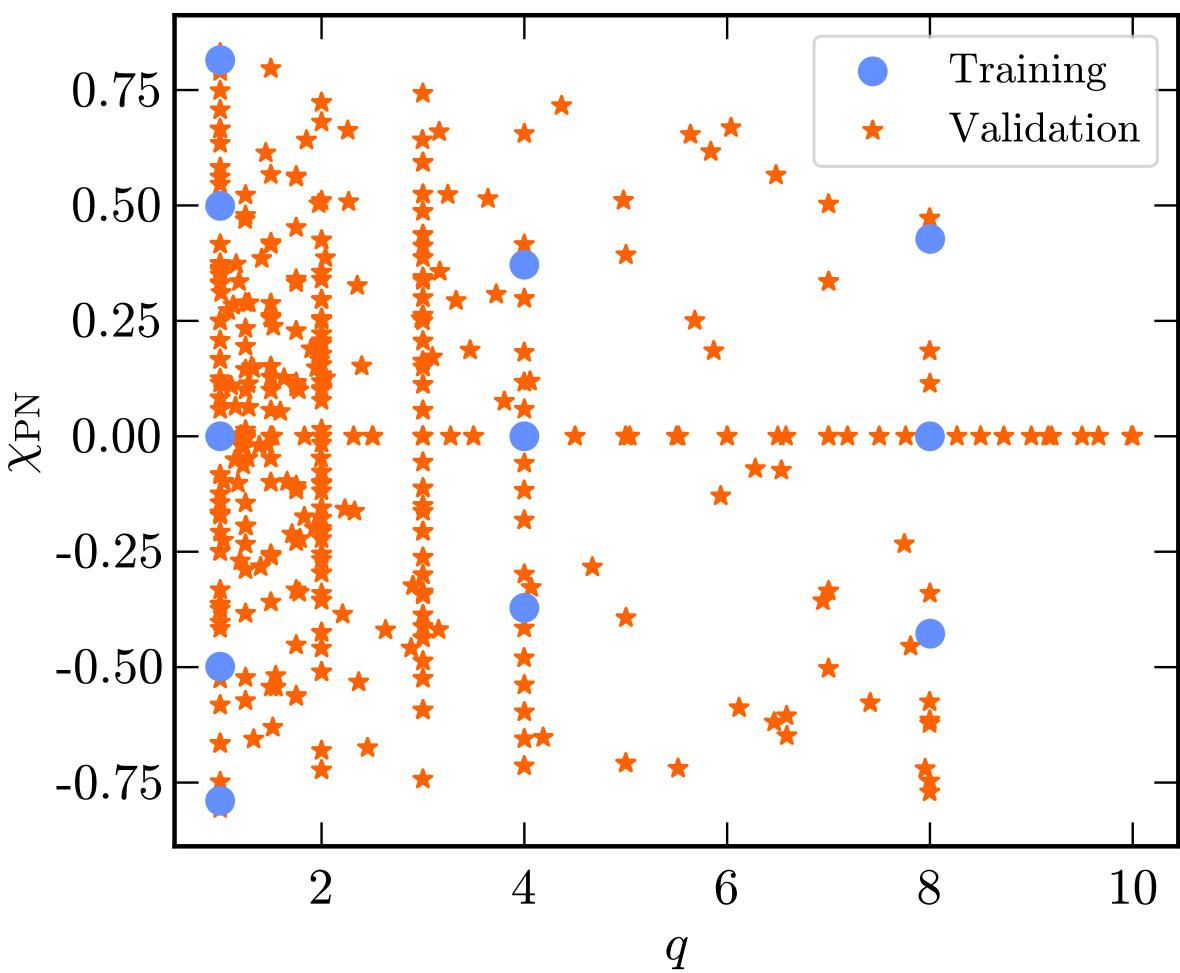










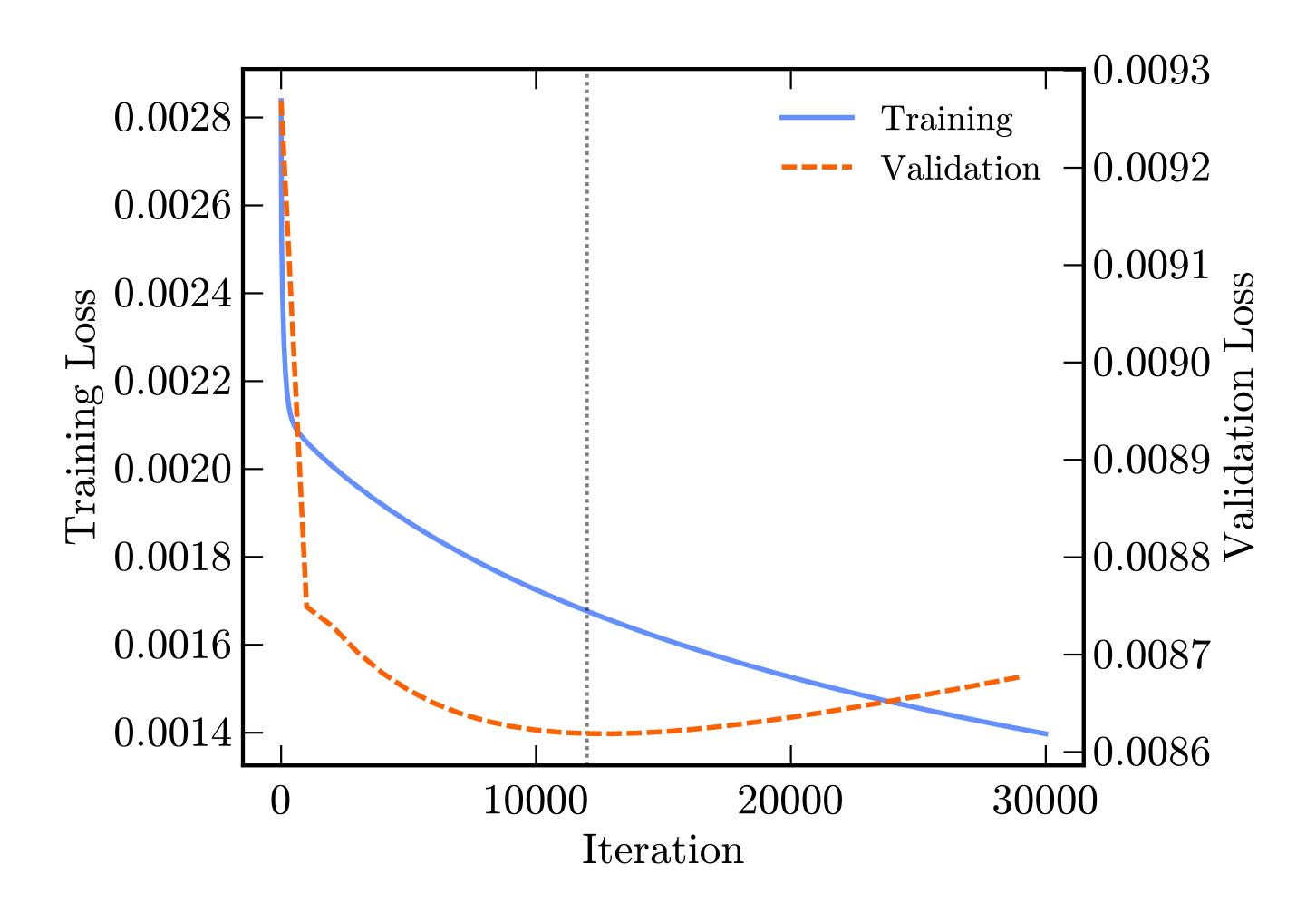






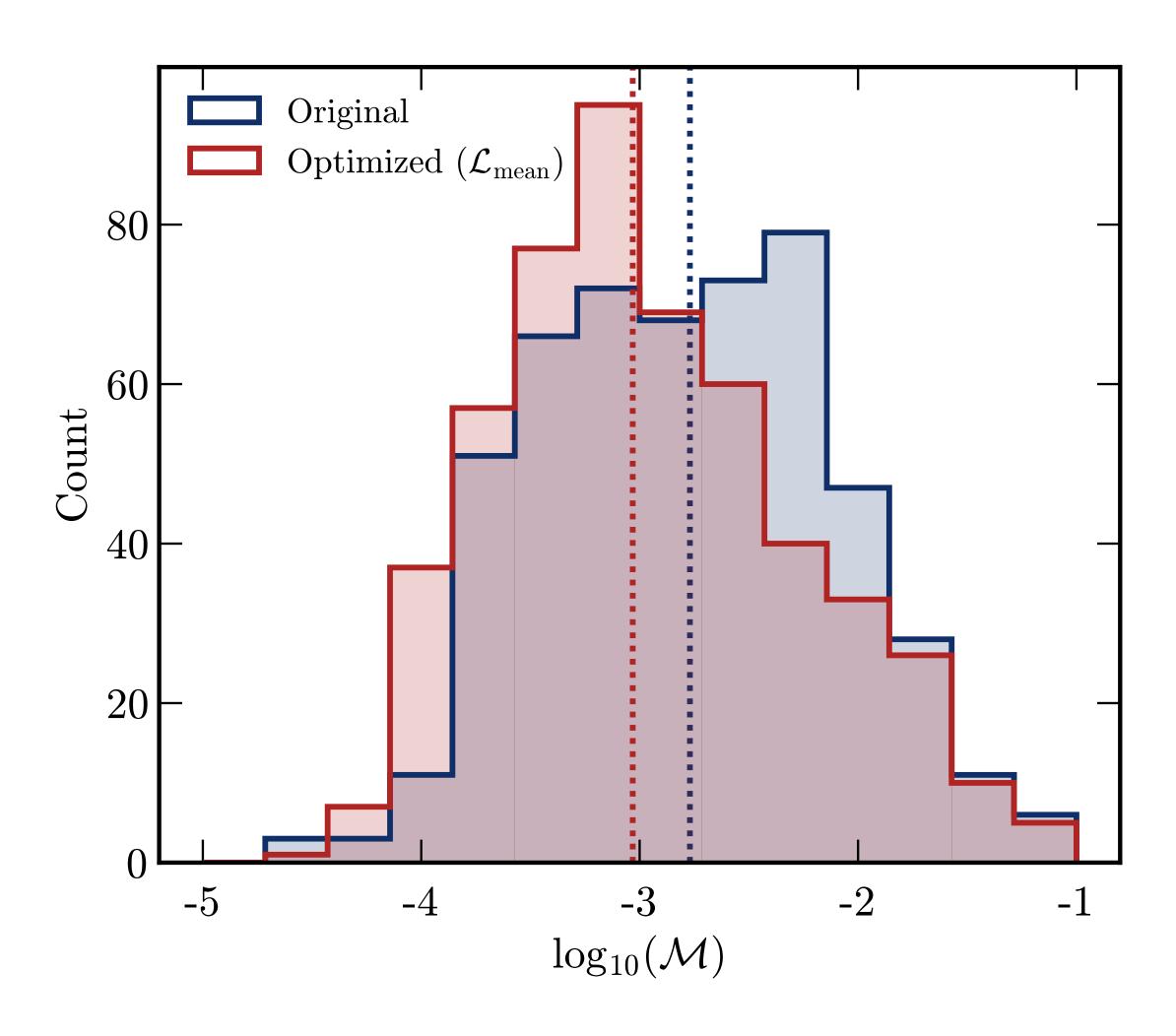
$$\lambda \to \lambda - \alpha \nabla \mathcal{L}$$







Up to 50% Better Waveforms For Free







$$p(\boldsymbol{\theta} \mid d) \propto p(d \mid \boldsymbol{\theta}) \pi(\boldsymbol{\theta})$$





$$p(\boldsymbol{\theta} \mid d) \propto p(d \mid \boldsymbol{\theta}) \pi(\boldsymbol{\theta})$$

= Likelihood





$$p(\boldsymbol{\theta} \mid d) \propto p(d \mid \boldsymbol{\theta}) \pi(\boldsymbol{\theta})$$

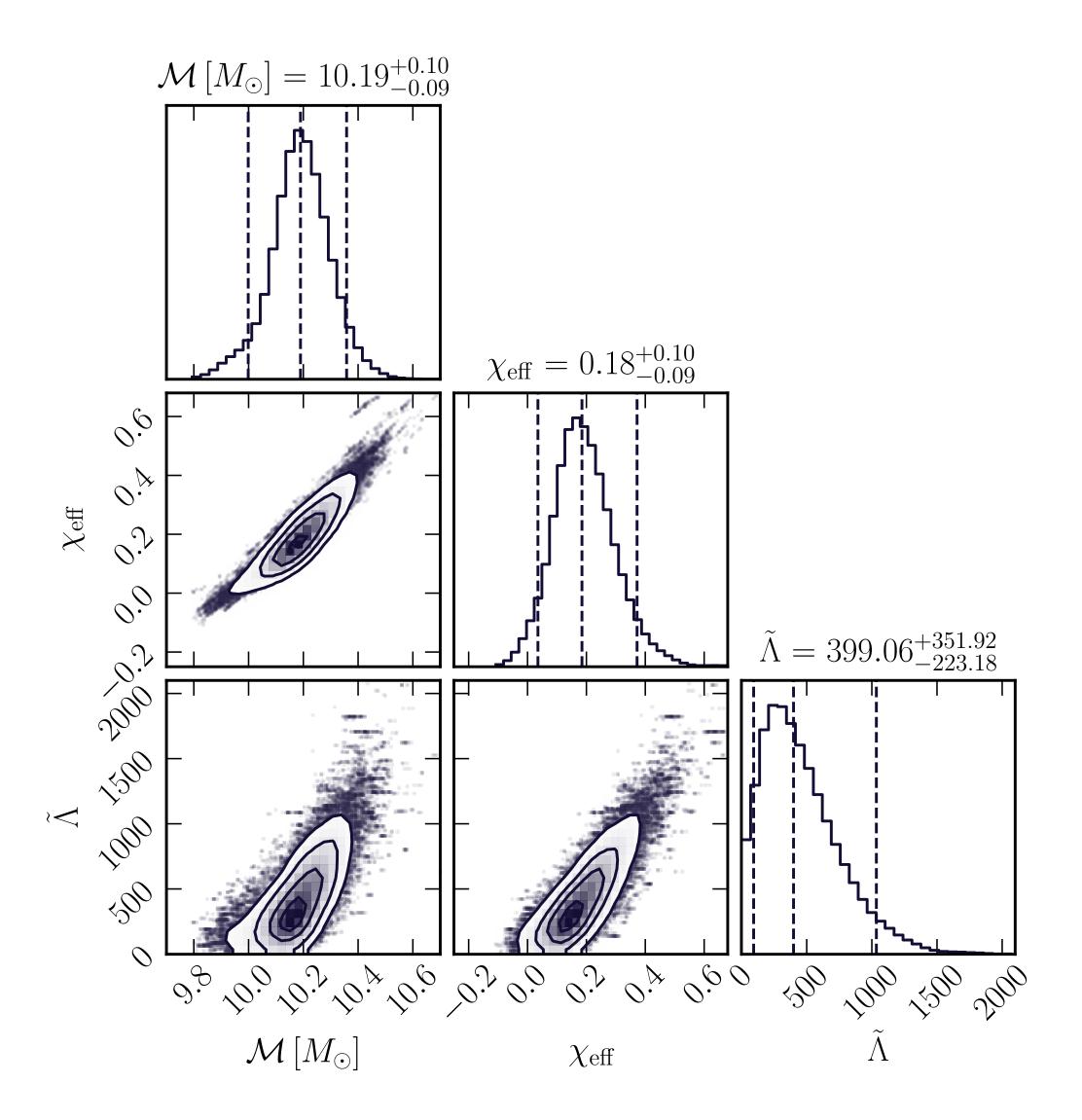
- = Likelihood
- O = Prior





$$p(\boldsymbol{\theta} \mid d) \propto p(d \mid \boldsymbol{\theta}) \pi(\boldsymbol{\theta})$$

- = Likelihood
- O = Prior



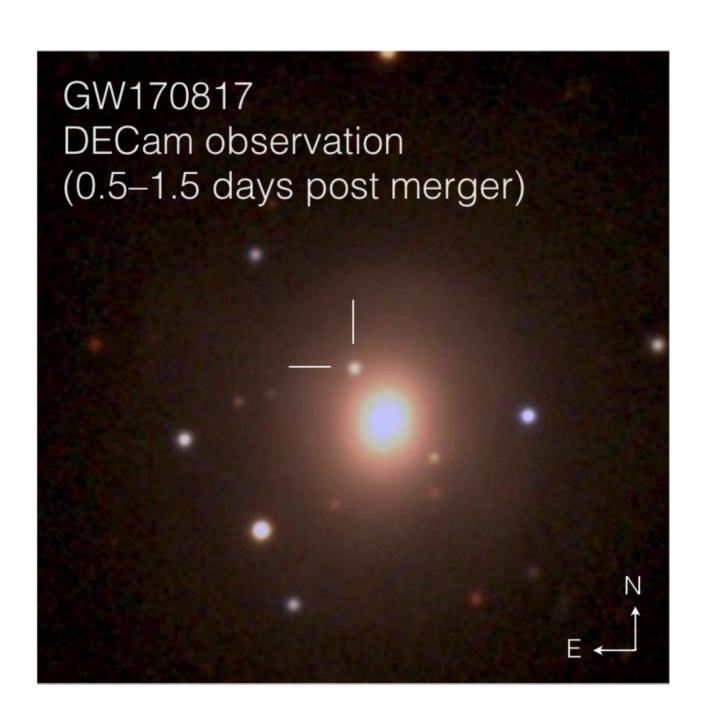
Why Accelerate PE?







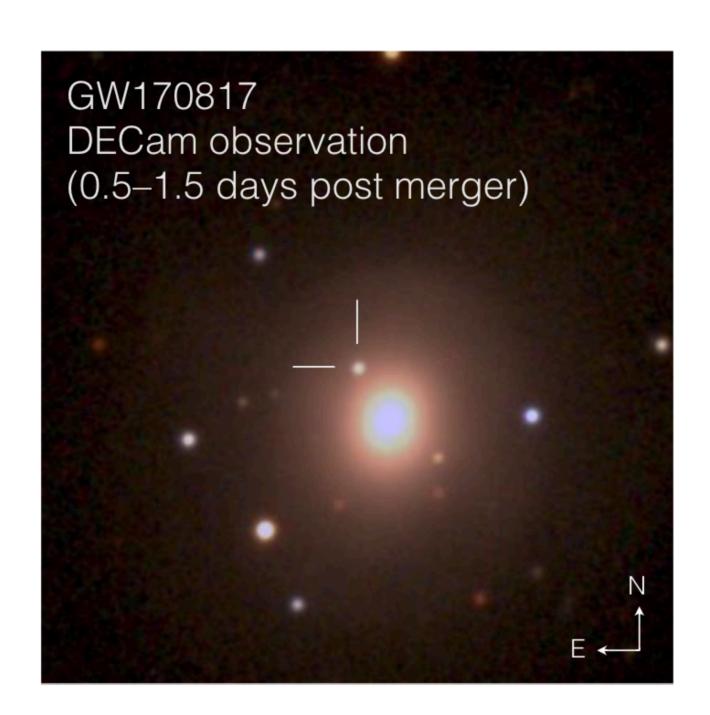
Low-latency follow up



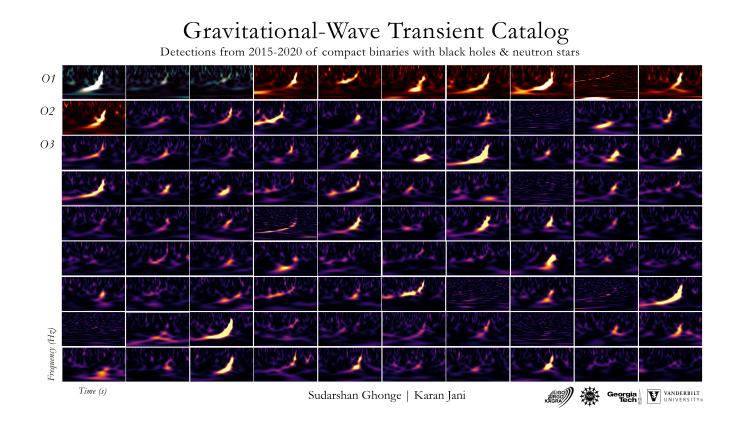




Low-latency follow up



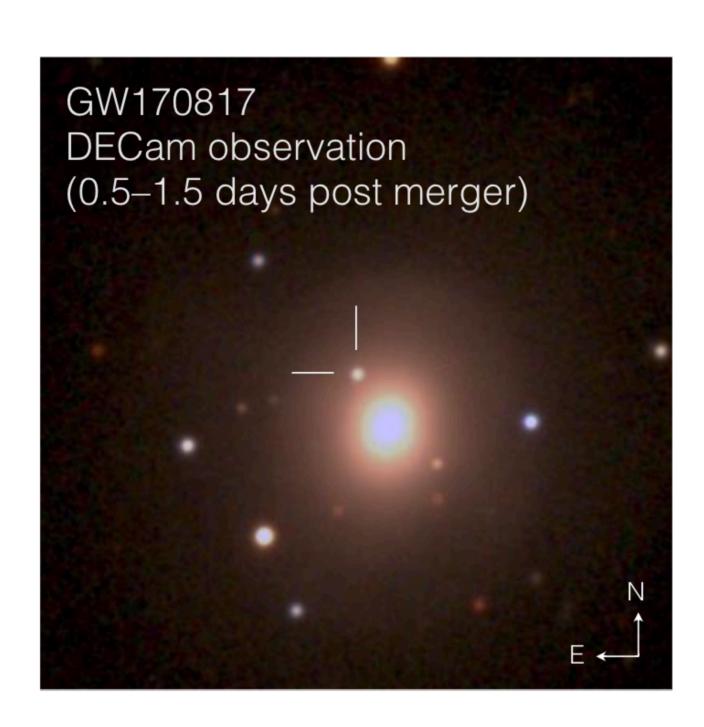
Overall compute



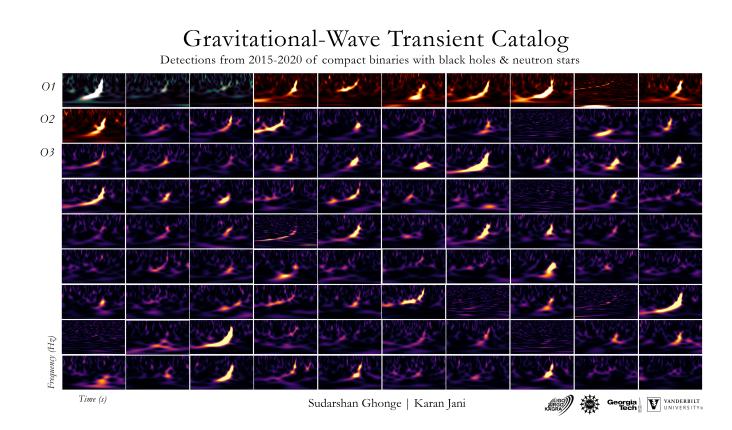




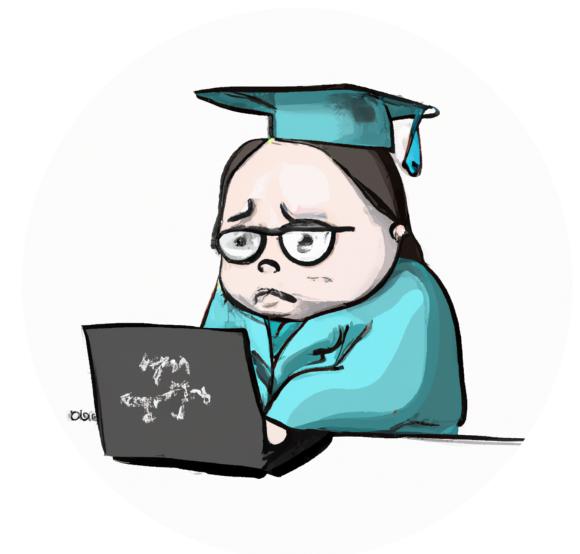
Low-latency follow up



Overall compute



Development cycle



flowMC





$$A\left(x',x\right) = \min\left(1, \frac{P\left(x'\right)}{P(x)} \frac{g\left(x \mid x'\right)}{g\left(x' \mid x\right)}\right)$$



flowMC





$$A\left(x',x\right) = \min\left(1, \frac{P\left(x'\right)}{P(x)} \frac{g\left(x \mid x'\right)}{g\left(x' \mid x\right)}\right)$$



flowMC



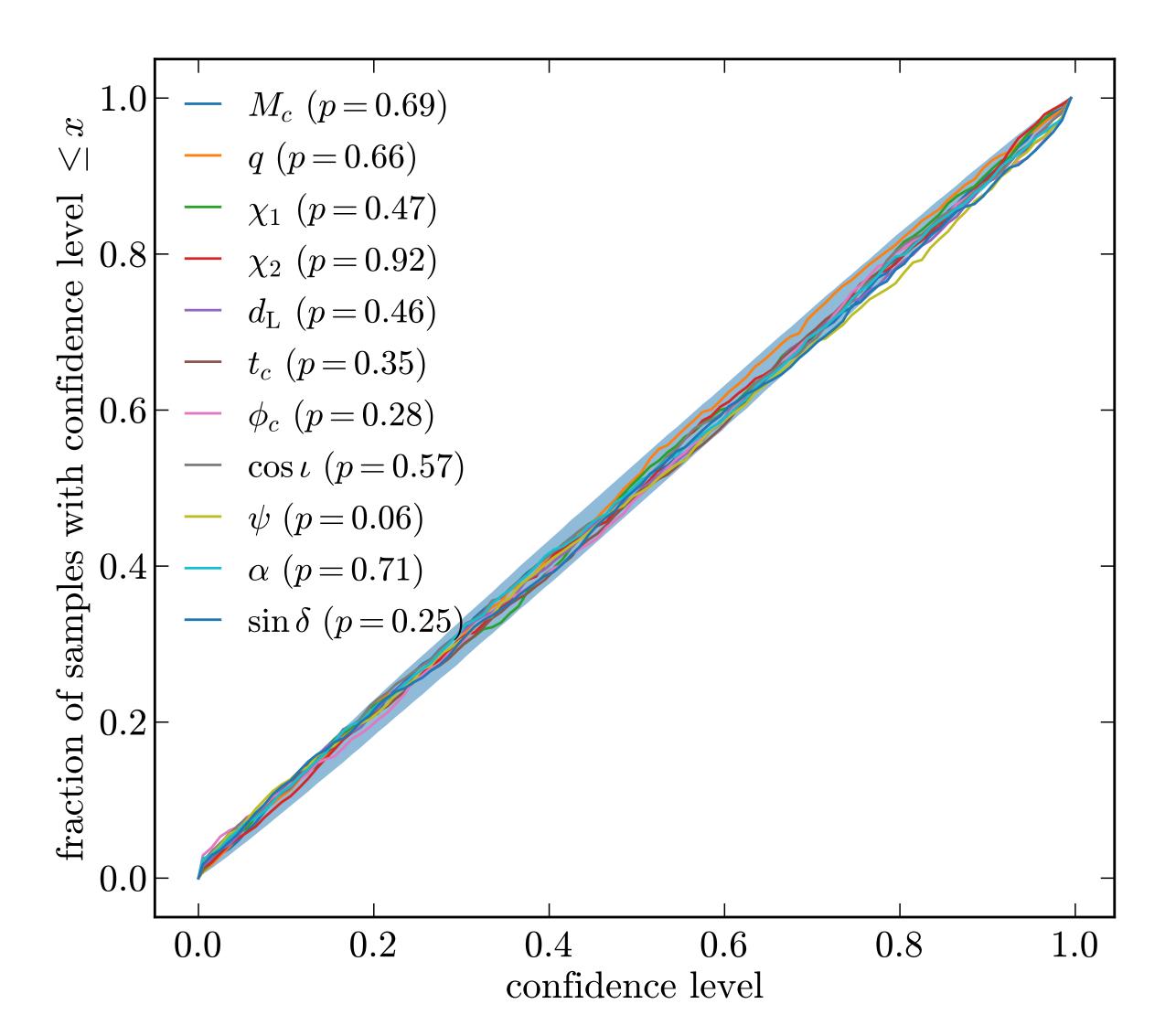


$$A\left(x',x\right) = \min\left(1, \frac{P\left(x'\right)}{P(x)} \frac{g\left(x \mid x'\right)}{g\left(x' \mid x\right)}\right)$$





For both BNS and BBH, we achieve converged results in ~1 min on an A100 GPU



Overview



How can automaticallydifferentiable models improve GW analysis tasks?



Kaze Wong



Max Isi

+ Kelvin K. H. Lam, Adam Coogan, James Alvey, and Daniel Foreman-Mackey

What could current searches be missing?



Horng Sheng Chia



Jay Wadekar



Aaron Zimmerman

Overview



How can automaticallydifferentiable models improve GW analysis tasks?



Kaze Wong



Max Isi

+ Kelvin K. H. Lam, Adam Coogan, James Alvey, and Daniel Foreman-Mackey

What could current searches be missing?



Horng Sheng Chia



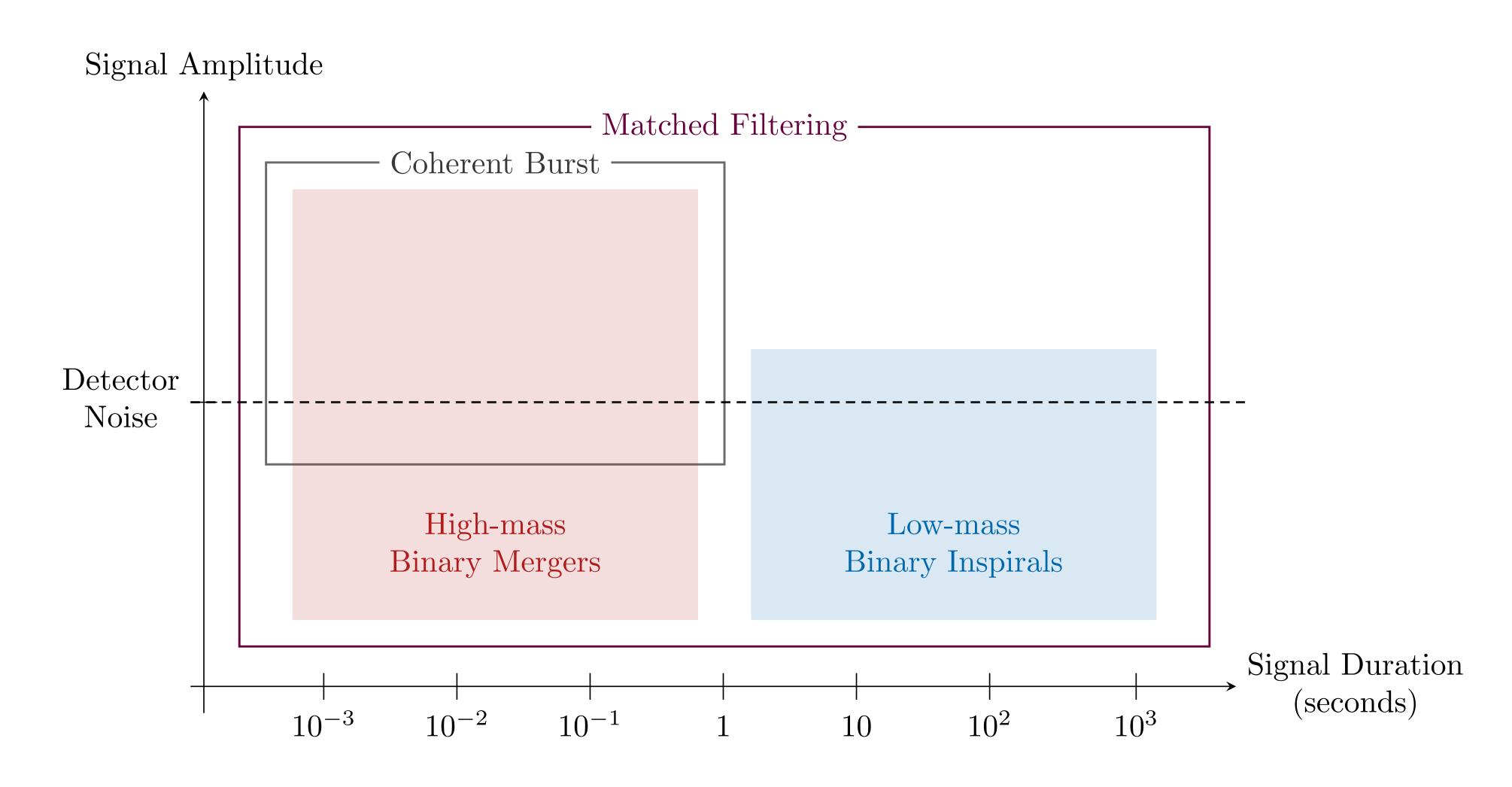
Jay Wadekar



Aaron Zimmerman





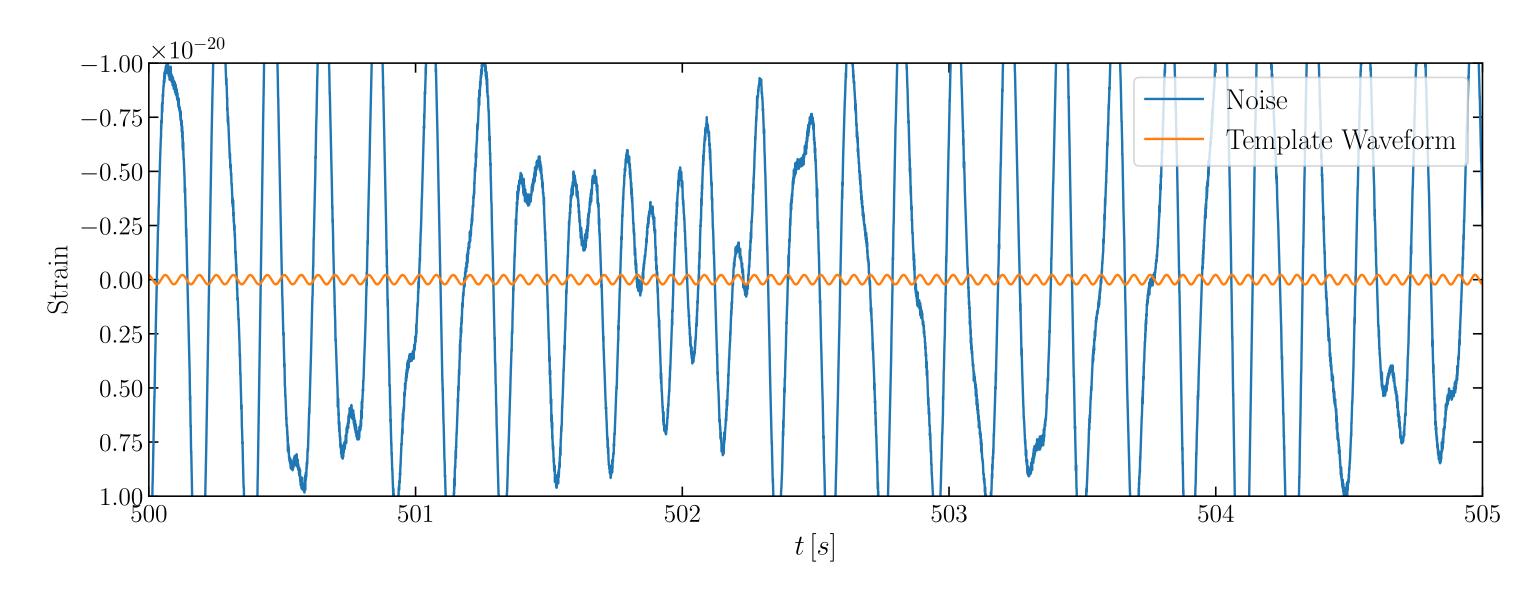


[**TE**, Chia (JCAP): 2004.06729]



Matched Filtering

Matched Filtering is the optimum technique for extracting known signals from stationary Gaussian noise

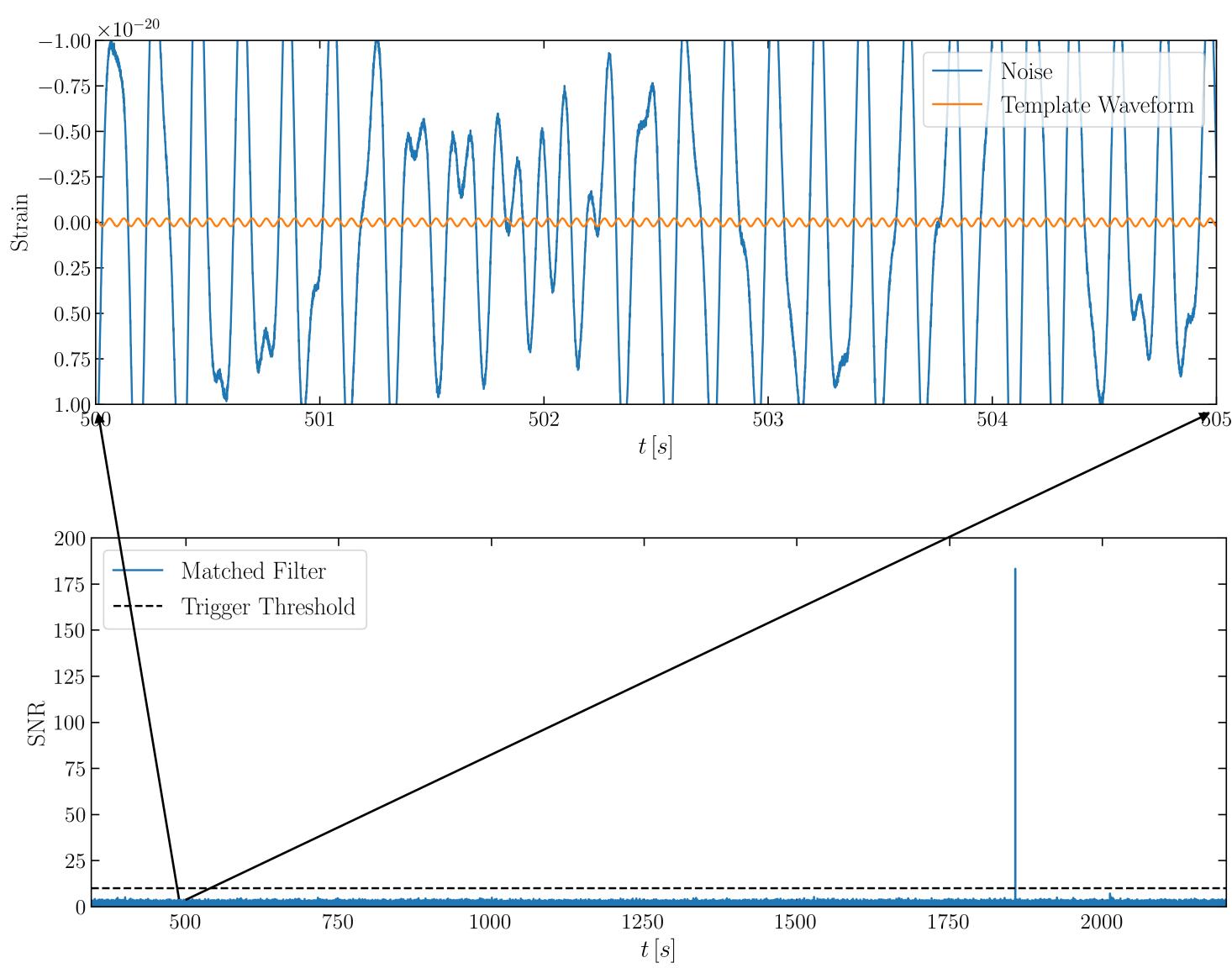


Matched Filtering



Matched Filtering is the optimum technique for extracting known signals from stationary Gaussian noise

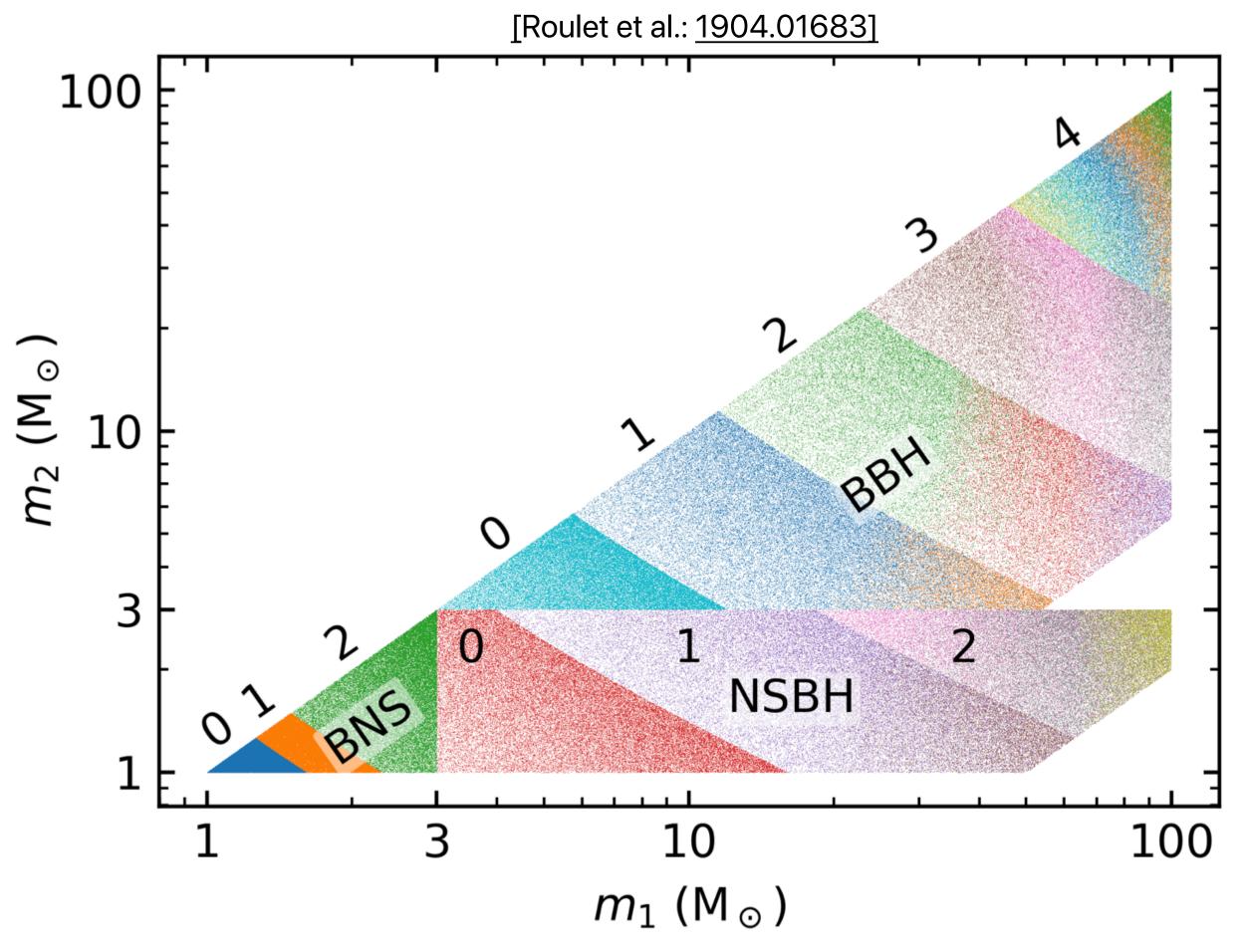
$$(h_1|h_2) \equiv 4 \operatorname{Re} \int_0^\infty df \frac{\tilde{h}_1(f)\tilde{h}_2^*(f)}{S_n(f)}$$





Effectualness/fitting-factor

The effectualness is the percentage of SNR retained by a template bank or model



$$\varepsilon \left(h_{\text{finite-size}} \right) \equiv \max_{t_c, \phi_c, \boldsymbol{p}_{\text{bbh}}} \left[h_{\text{finite-size}} \mid h \left(\boldsymbol{p}_{\text{bbh}} \right) \right]$$





$$\tilde{h}(f; \boldsymbol{p}) = \mathcal{A}(\boldsymbol{p})e^{i\phi(f; \boldsymbol{p})}$$

$$egin{aligned} \mathcal{A}(f;m{p},m{\lambda}) &\propto \mathcal{A}_{\mathrm{PN}}(m{p}) \ &+ \mathcal{A}_{\mathrm{Int}}(m{\lambda}) + \mathcal{A}_{\mathrm{MR}}(m{\lambda}) \ \end{pmatrix} & \phi(f;m{p},m{\lambda}) &\propto \phi_{\mathrm{PN}}(m{p}) \ &+ \phi_{\mathrm{Int}}(m{\lambda}) + \phi_{\mathrm{MR}}(m{\lambda}) \end{aligned}$$





$$\tilde{h}(f; \boldsymbol{p}) = \mathcal{A}(\boldsymbol{p})e^{i\phi(f; \boldsymbol{p})}$$

$$egin{aligned} \mathcal{A}(f;m{p},m{\lambda}) \propto \mathcal{A}_{ ext{PN}}(m{p}) \ &+ \mathcal{A}_{ ext{Int}}(m{\lambda}) + \mathcal{A}_{ ext{MR}}(m{\lambda}) \ &+ \phi_{ ext{Int}}(m{\lambda}) + \phi_{ ext{MR}}(m{\lambda}) \end{aligned}$$





$$\tilde{h}(f; \boldsymbol{p}) = \mathcal{A}(\boldsymbol{p})e^{i\phi(f; \boldsymbol{p})}$$

$$egin{aligned} \mathcal{A}(f;m{p},m{\lambda}) \propto \mathcal{A}_{ ext{PN}}(m{p}) \ &+ \mathcal{A}_{ ext{Int}}(m{\lambda}) + \mathcal{A}_{ ext{MR}}(m{\lambda}) \ \end{pmatrix} &+ \phi_{ ext{Int}}(m{\lambda}) + \phi_{ ext{MR}}(m{\lambda}) \end{aligned}$$

$$\phi(f; \boldsymbol{p}) = 2\pi f t_c - \phi_c - \frac{\pi}{4} + \frac{3}{128\nu v^5} \left(\phi_{\text{point-particle}} + \phi_{\text{finite-size}}\right)$$





$$\tilde{h}(f; \boldsymbol{p}) = \mathcal{A}(\boldsymbol{p})e^{i\phi(f; \boldsymbol{p})}$$

$$\phi(f; \boldsymbol{p}) = 2\pi f t_c - \phi_c - \frac{\pi}{4} + \frac{3}{128\nu v^5} \left(\phi_{\text{point-particle}} + \phi_{\text{finite-size}}\right)$$





$$\tilde{h}(f; \boldsymbol{p}) = \mathcal{A}(\boldsymbol{p})e^{i\phi(f; \boldsymbol{p})}$$

$$\phi(f; \boldsymbol{p}) = 2\pi f t_c - \phi_c - \frac{\pi}{4} + \frac{3}{128\nu v^5} \left(\phi_{\text{point-particle}} + \phi_{\text{finite-size}}\right)$$

$$\phi_{\text{point-particle}} \propto \sum_{n} \phi_{n} v^{n}$$

$$\phi_{\text{finite-size}} \supset -50 \sum_{i=1}^{2} \left(\frac{m_{i}}{M}\right)^{2} \kappa_{i} \chi_{i}^{2} v^{4} - \frac{39\tilde{\Lambda}}{2} v^{10}$$





$$\tilde{h}(f; \boldsymbol{p}) = \mathcal{A}(\boldsymbol{p})e^{i\phi(f; \boldsymbol{p})}$$

$$\phi_{\text{finite-size}} \supset -50 \sum_{i=1}^{2} \left(\frac{m_i}{M}\right)^2 \kappa_i \chi_i^2 v^4 - \frac{39\tilde{\Lambda}}{2} v^{10}$$

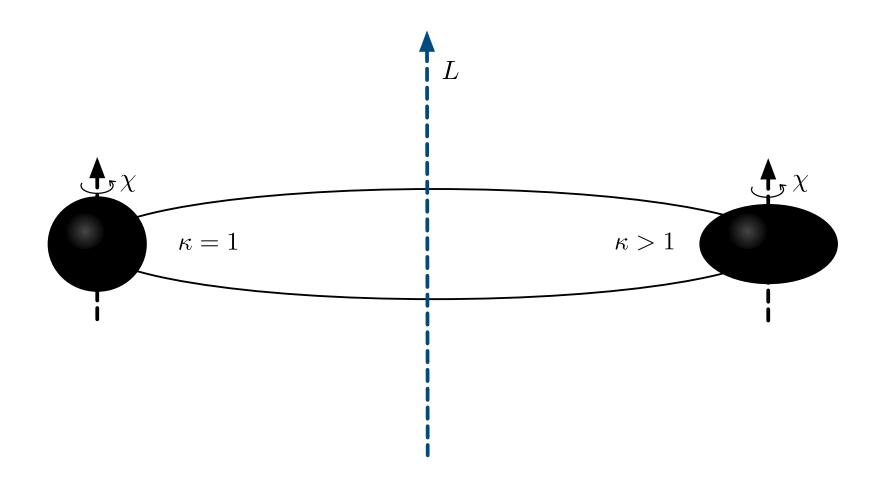




$$\tilde{h}(f; \boldsymbol{p}) = \mathcal{A}(\boldsymbol{p})e^{i\phi(f; \boldsymbol{p})}$$

$$\phi_{\text{finite-size}} \supset -50 \sum_{i=1}^{2} \left(\frac{m_i}{M}\right)^2 \kappa_i \chi_i^2 v^4 - \frac{39\tilde{\Lambda}}{2} v^{10}$$

Spin Induced Quadruple



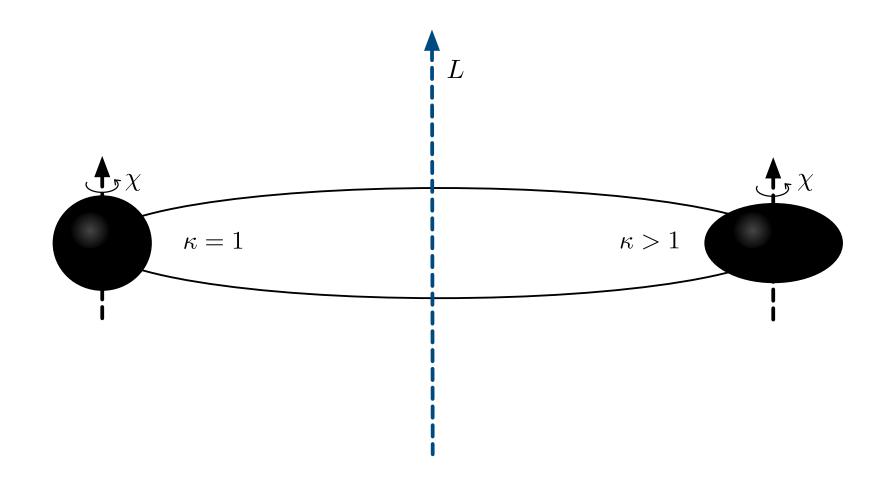




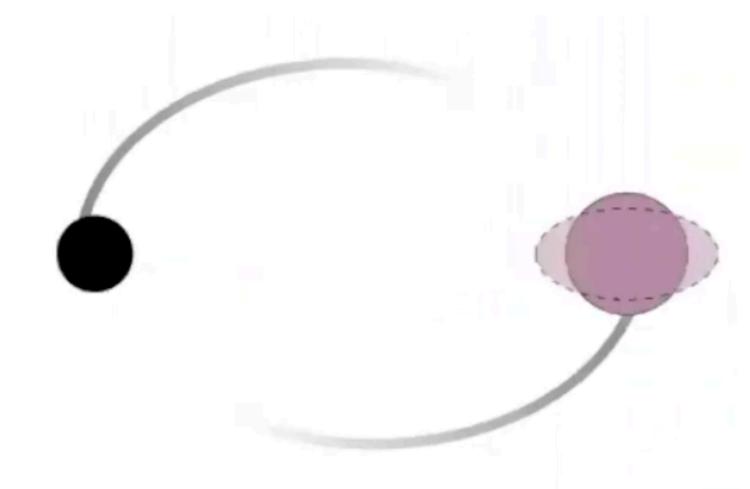
$$\tilde{h}(f; \boldsymbol{p}) = \mathcal{A}(\boldsymbol{p})e^{i\phi(f; \boldsymbol{p})}$$

$$\phi_{\text{finite-size}} \supset -50 \sum_{i=1}^{2} \left(\frac{m_i}{M}\right)^2 \kappa_i \chi_i^2 v^4 - \frac{39\tilde{\Lambda}}{2} v^{10}$$

Spin Induced Quadruple

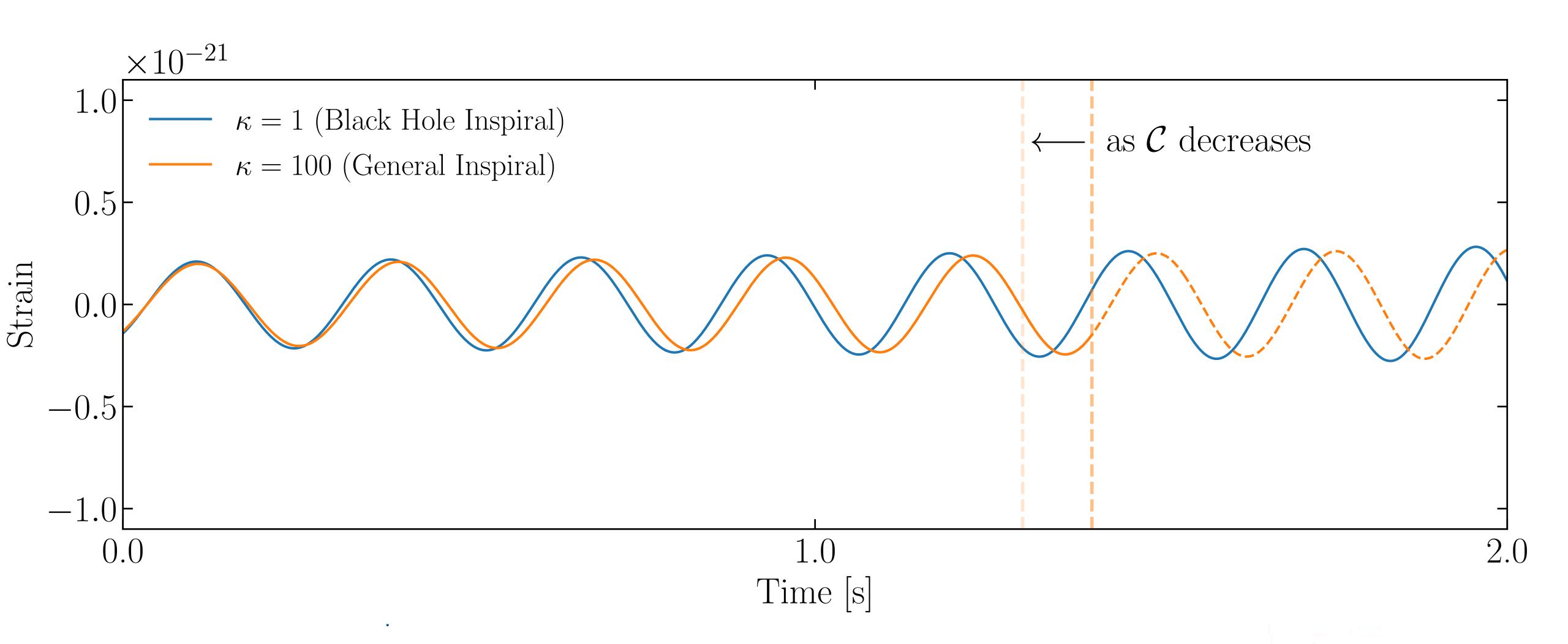


Tidal Love Number





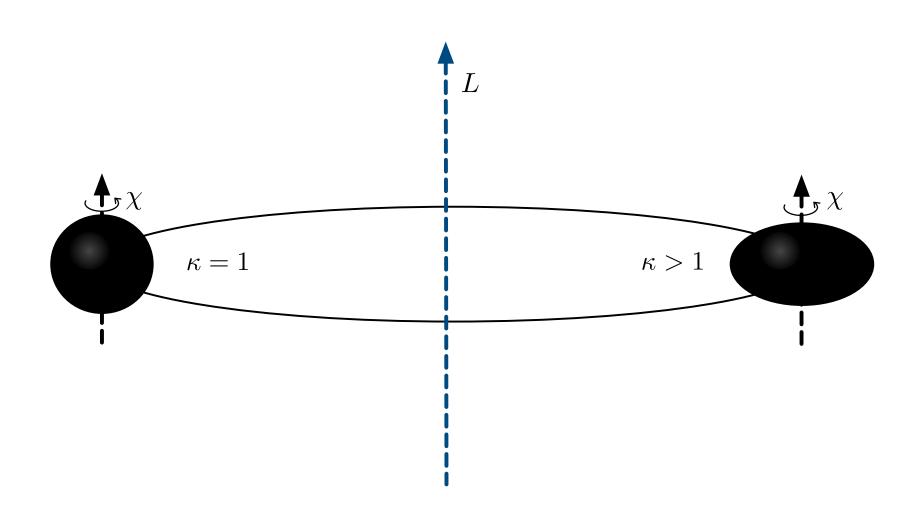


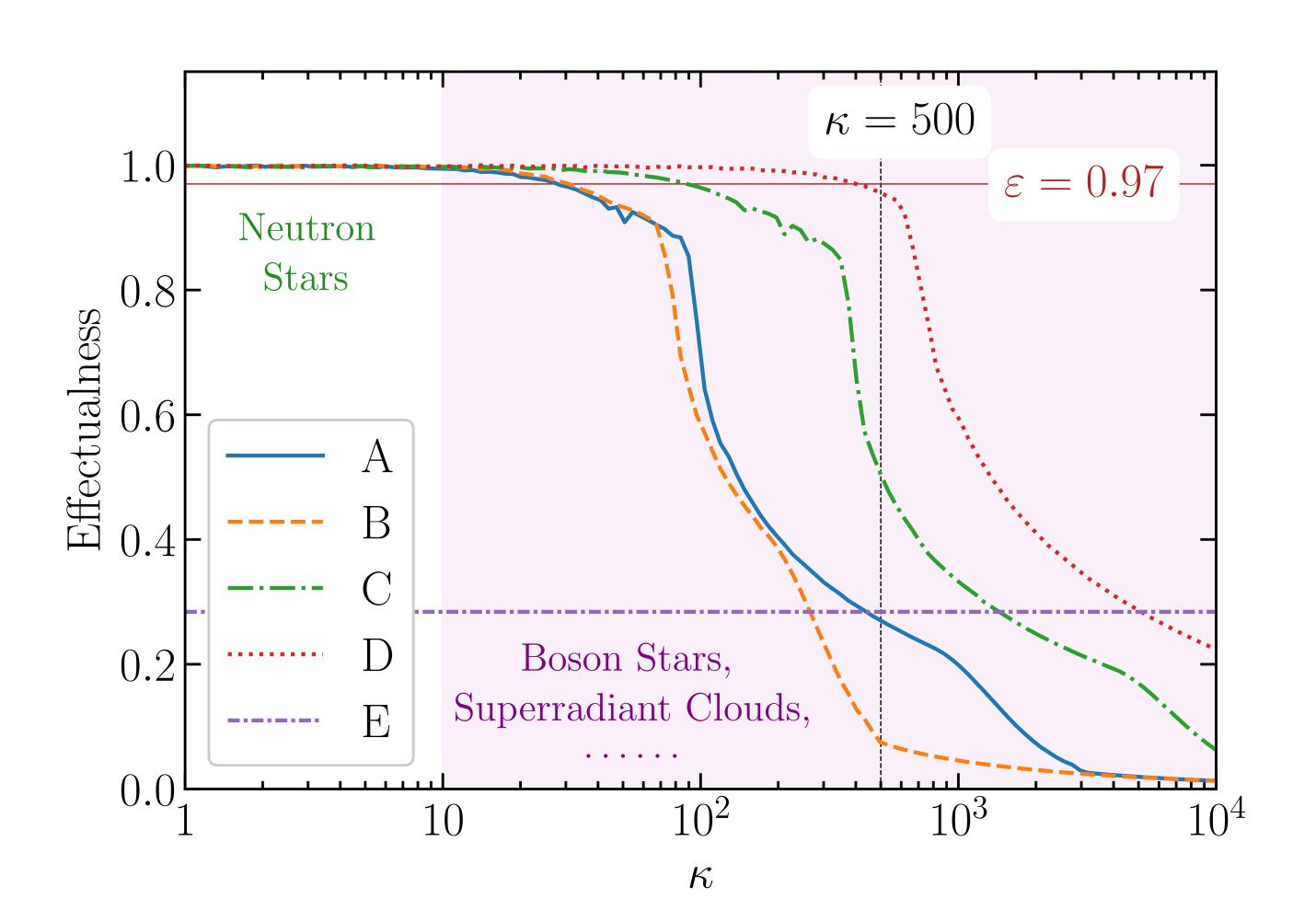




Spin-Induced Quadrupoles

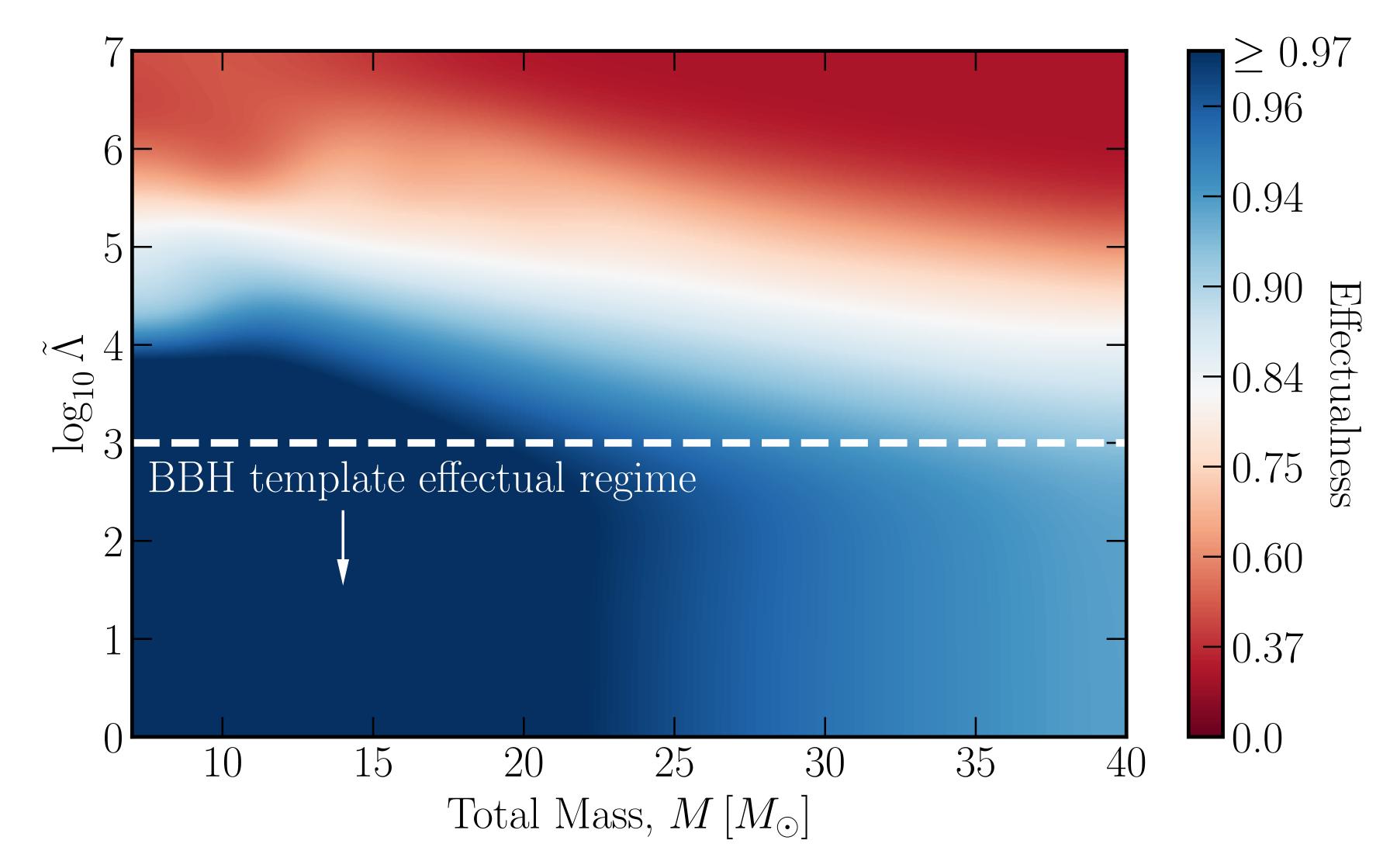
Kappa controls the axisymmetric response of an object to spin *i.e.*, how oblate it becomes







Tidal Love Numbers





$$\Lambda = \frac{2}{3}k\left(\frac{r}{m}\right)^5$$



$$\Lambda = \frac{2}{3}k\left(\frac{r}{m}\right)^5$$

 $oldsymbol{0} = O(1)$ coefficient



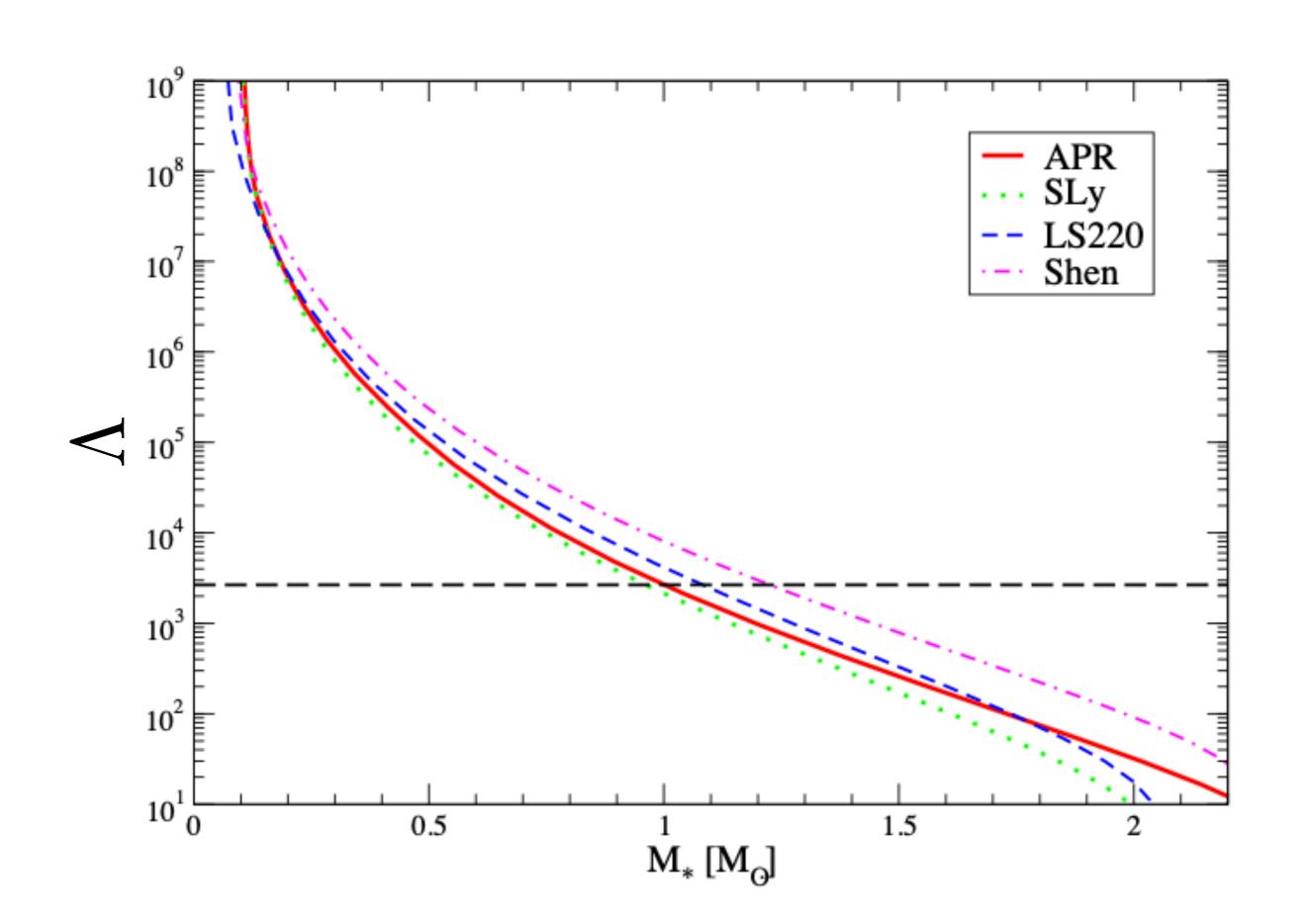
$$\Lambda = \frac{2}{3}k\left(\frac{r}{m}\right)^5$$

- $oldsymbol{0} = O(1)$ coefficient
- Object's radius



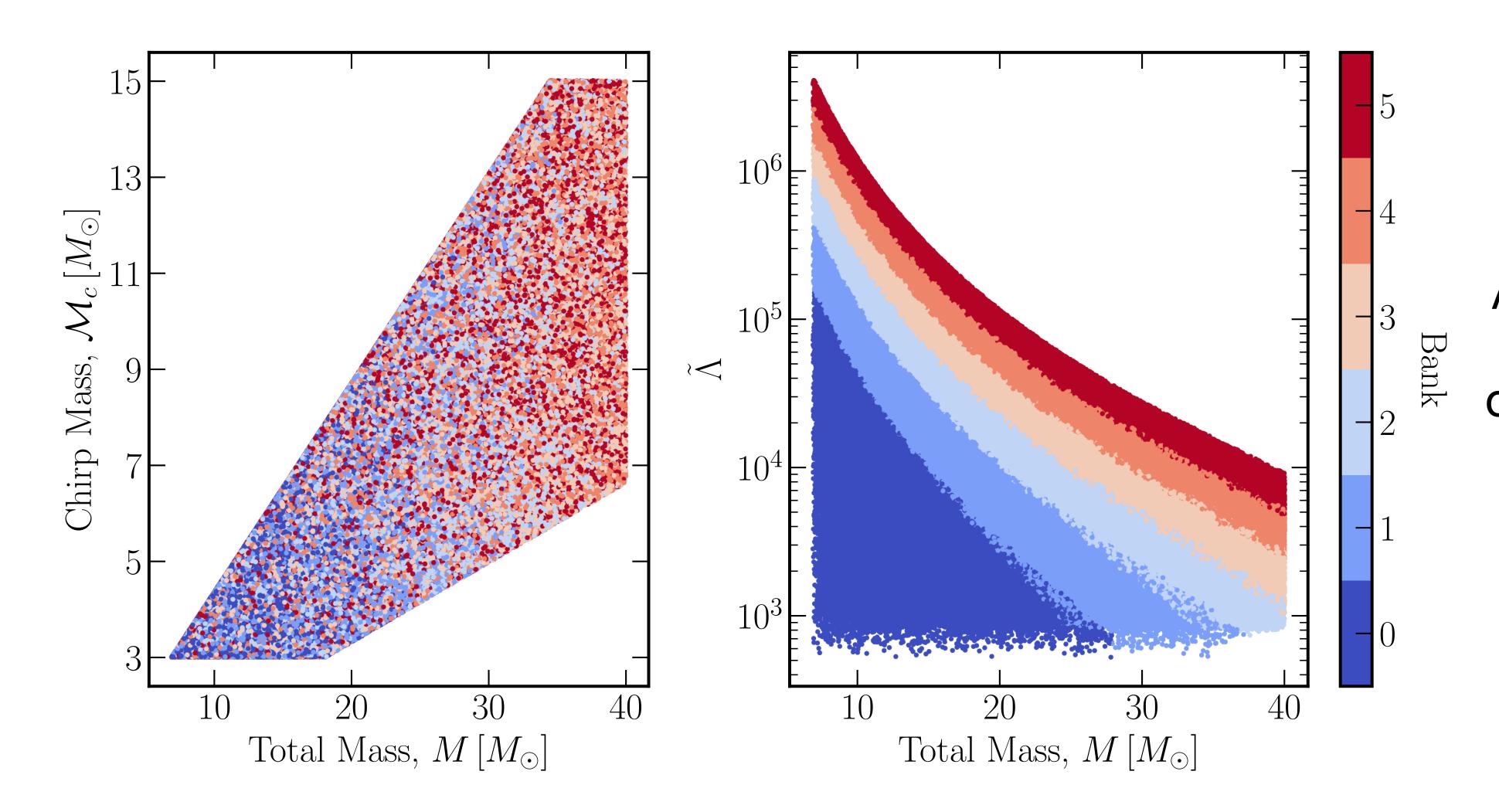
$$\Lambda = \frac{2}{3}k\left(\frac{r}{m}\right)^5$$

- $oldsymbol{o}$ = O(1) coefficient
- Object's radius







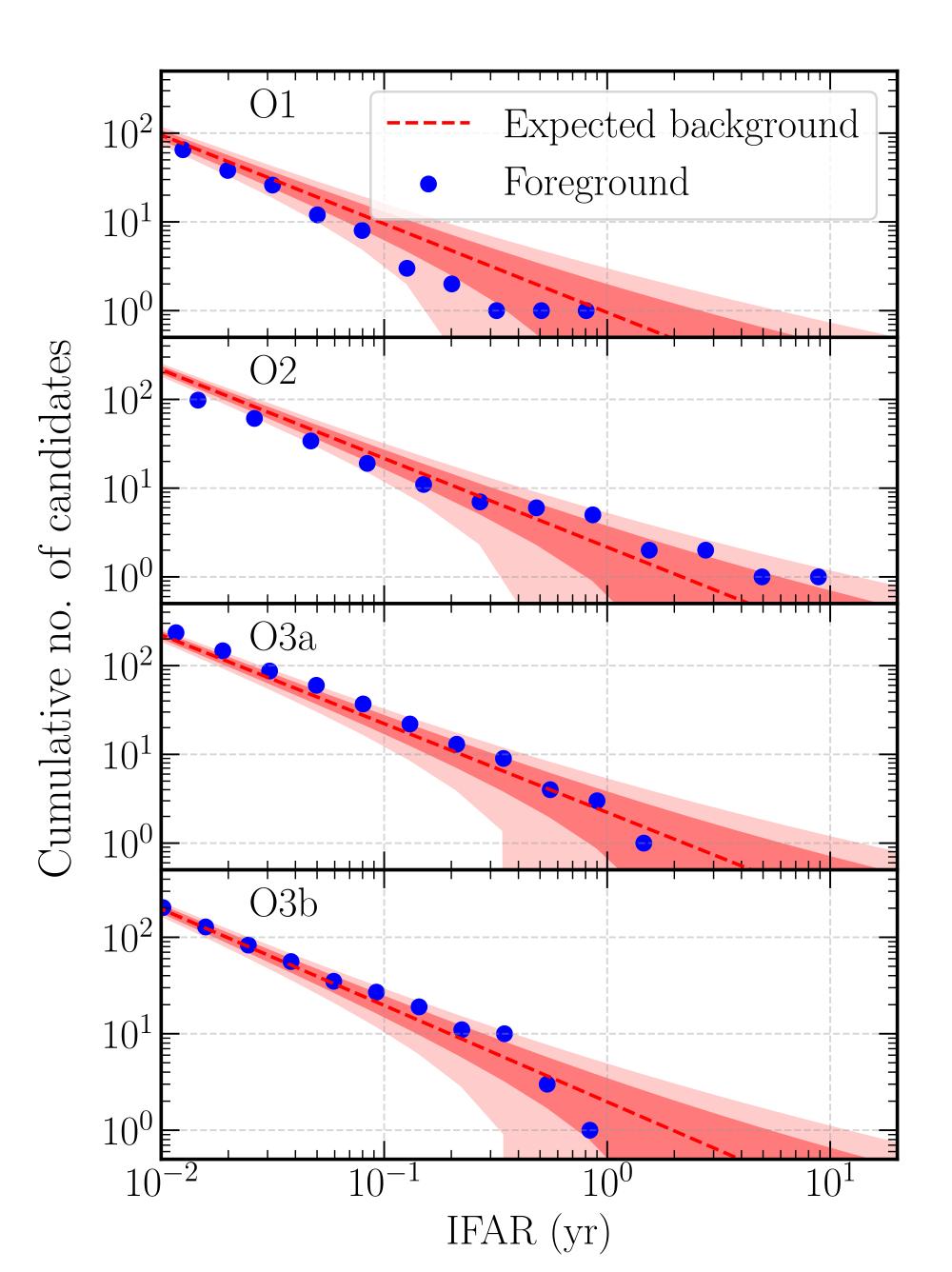


Anything outside this space we cannot guarantee coverage



We performed the first inspiralonly search for signals that are **not** aligned-spin BBHs

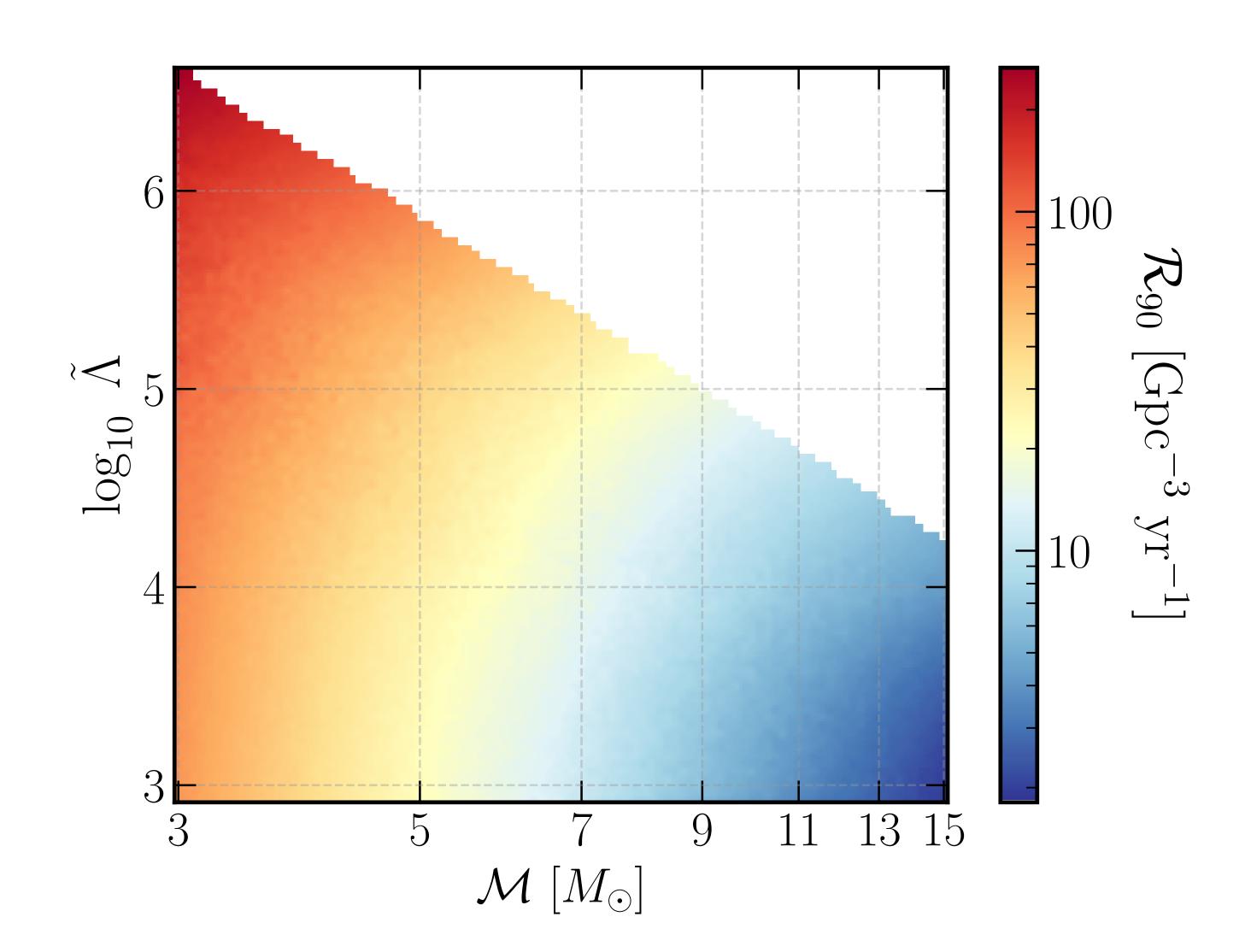
No significant candidates found





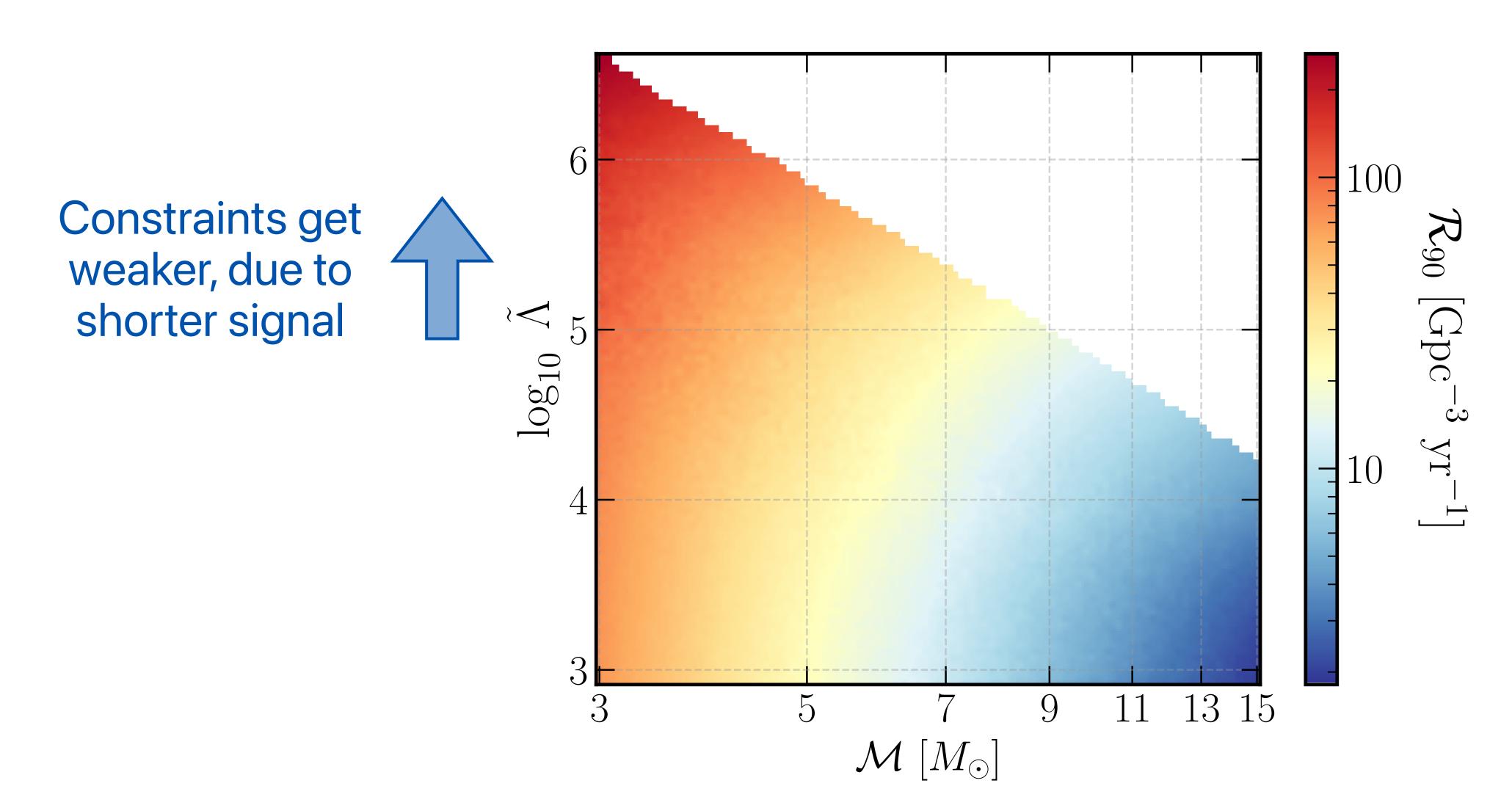


Rate Constraints





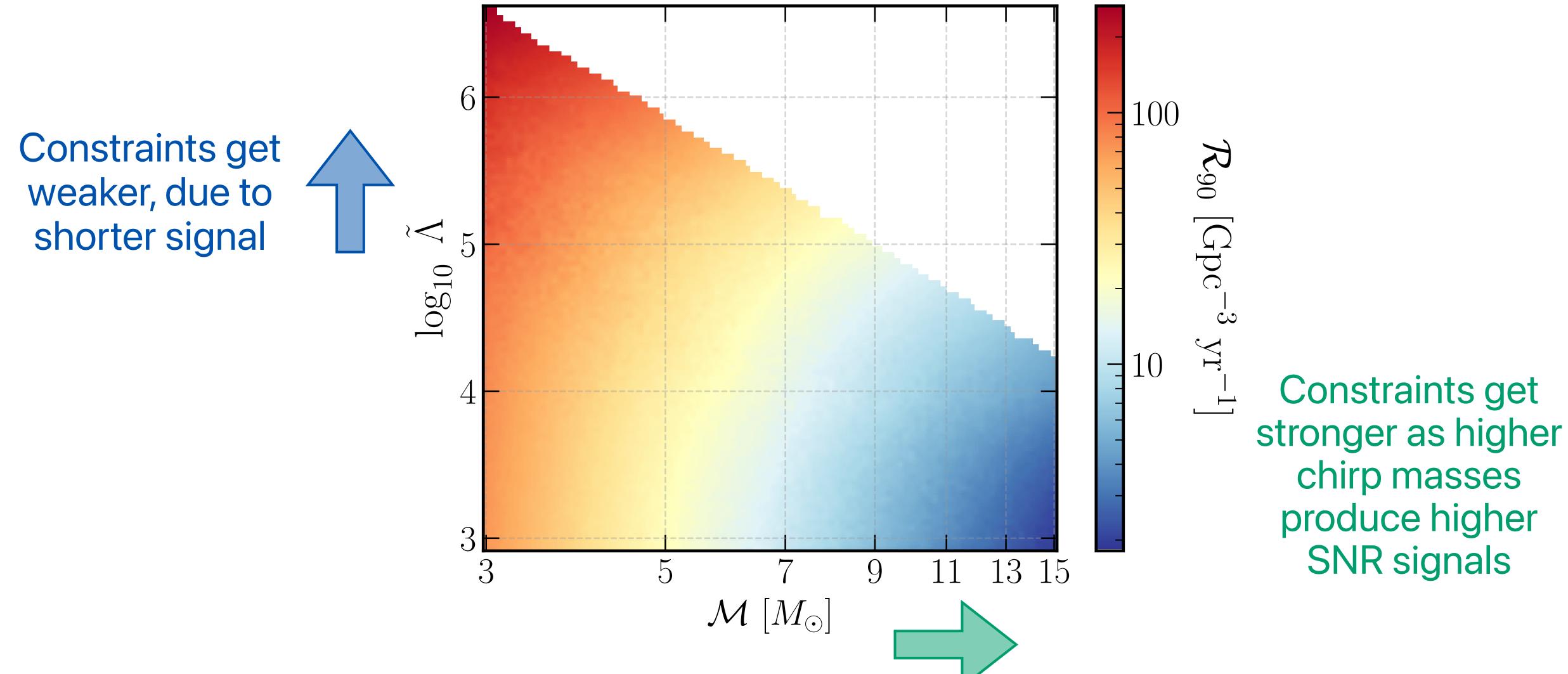




27

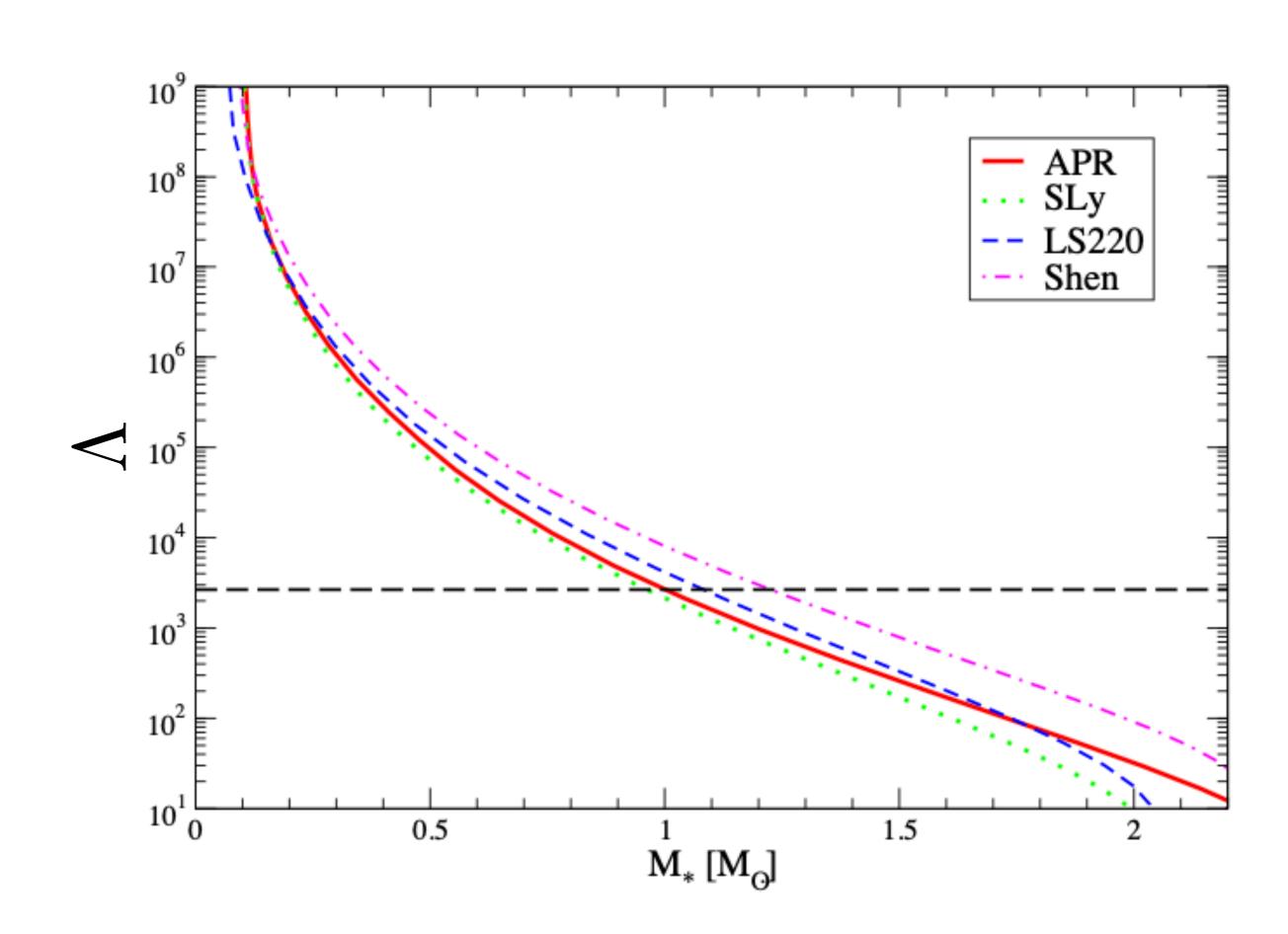








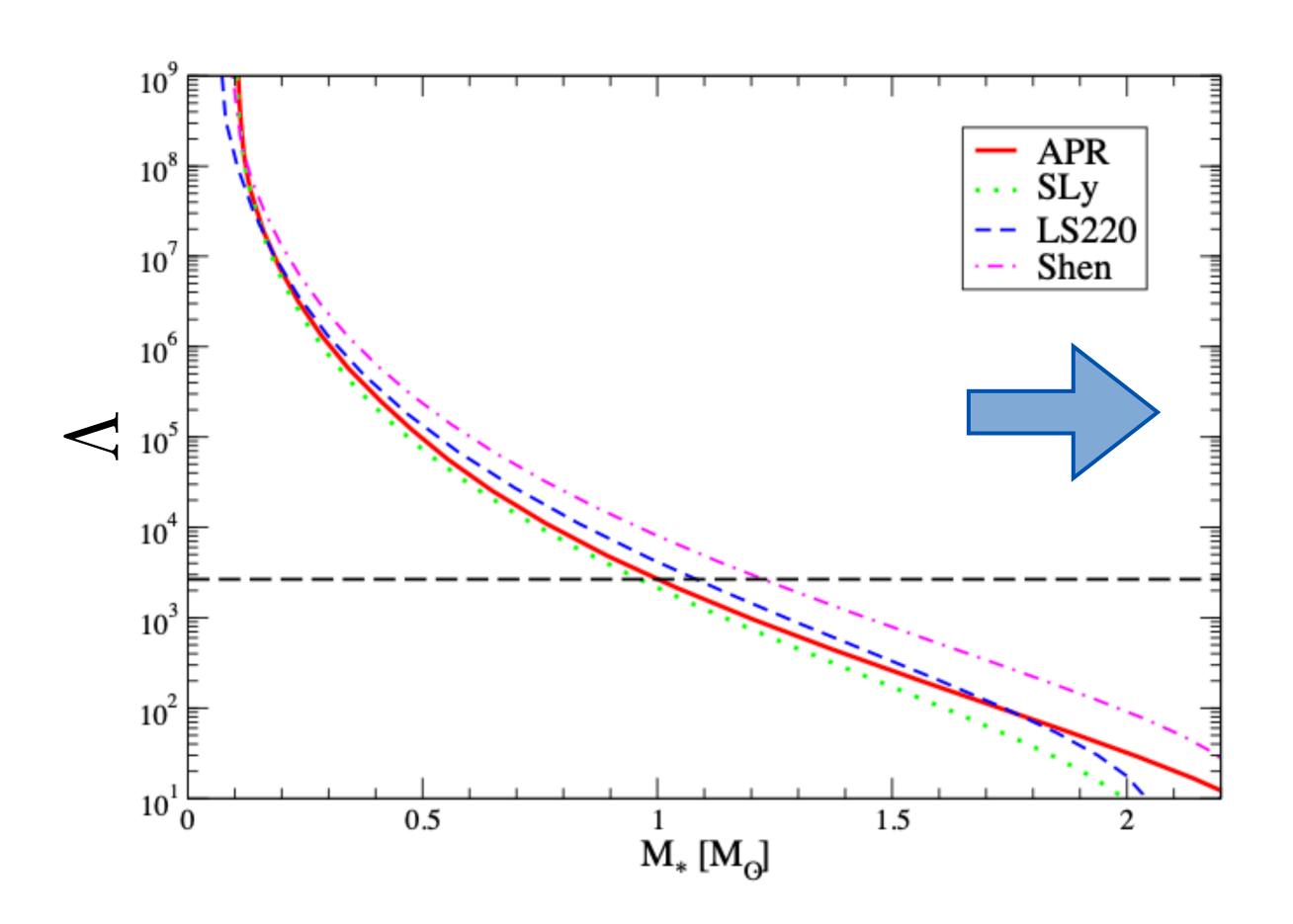








We have currently search in the high-mass region of parameter space due to computational limitations

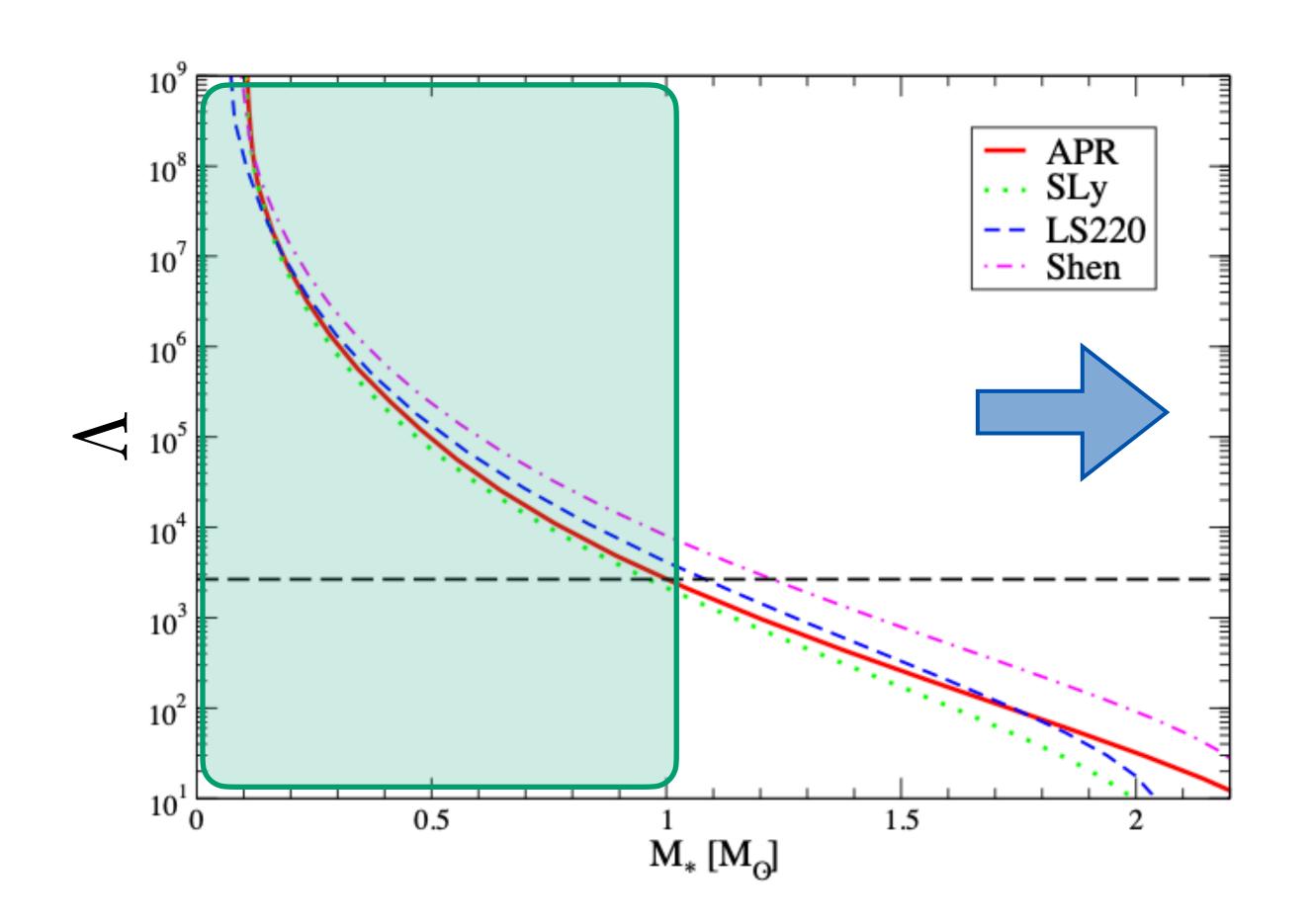






We have currently search in the high-mass region of parameter space due to computational limitations

Future searchers should focus on the low-mass region, where neutron stars may be hiding















- Waveform developers should start to use pure python (or JAX) for public release
- Real time PE processing could potentially replace matched filtering search pipelines





- Waveform developers should start to use pure python (or JAX) for public release
- Real time PE processing could potentially replace matched filtering search pipelines

Searches, especially at low masses, are currently limited by their template bank coverage





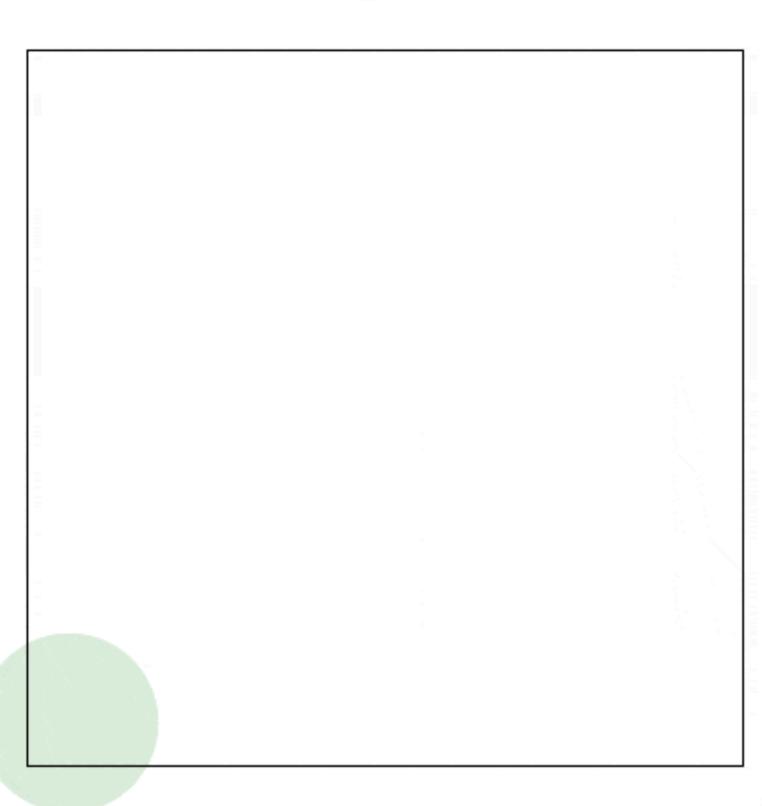
- Waveform developers should start to use pure python (or JAX) for public release
- Real time PE processing could potentially replace matched filtering search pipelines

Searches, especially at low masses, are currently limited by their template bank coverage

- Many more searches to be done in order to fully utilize the GW data we have
- Low-mass neutron stars are a great target for a future Love numbers search







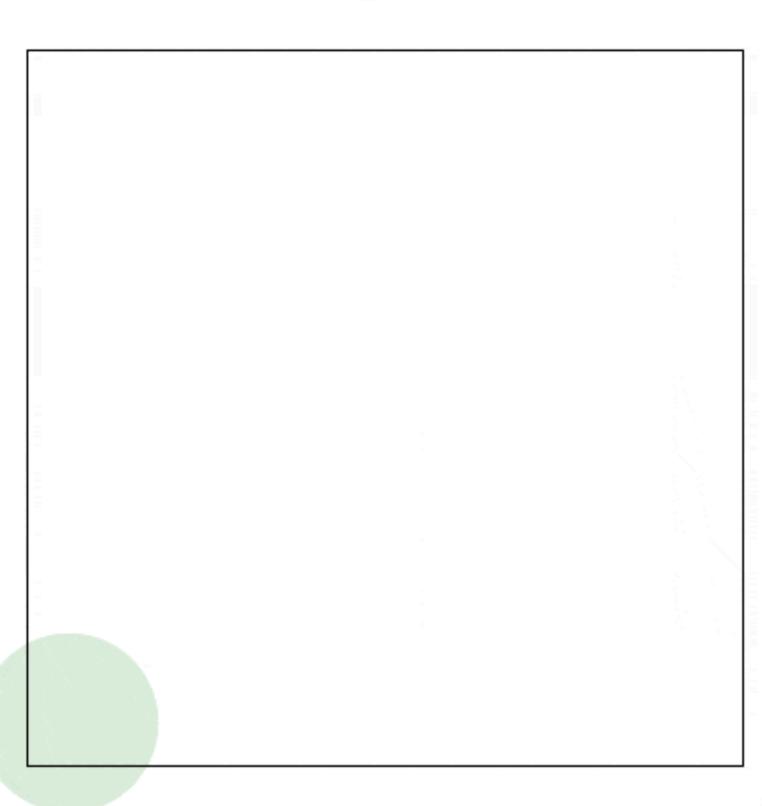
- Quick to generate
- Can achieve ~100% coverage
- Placement of points in highly curved spaces unknown or difficult
- Require a known metric

[Cokelaer: <u>0706.4437</u>]

[Owen: <u>9511032</u>]







- Quick to generate
- Can achieve ~100% coverage
- Placement of points in highly curved spaces unknown or difficult
- Require a known metric

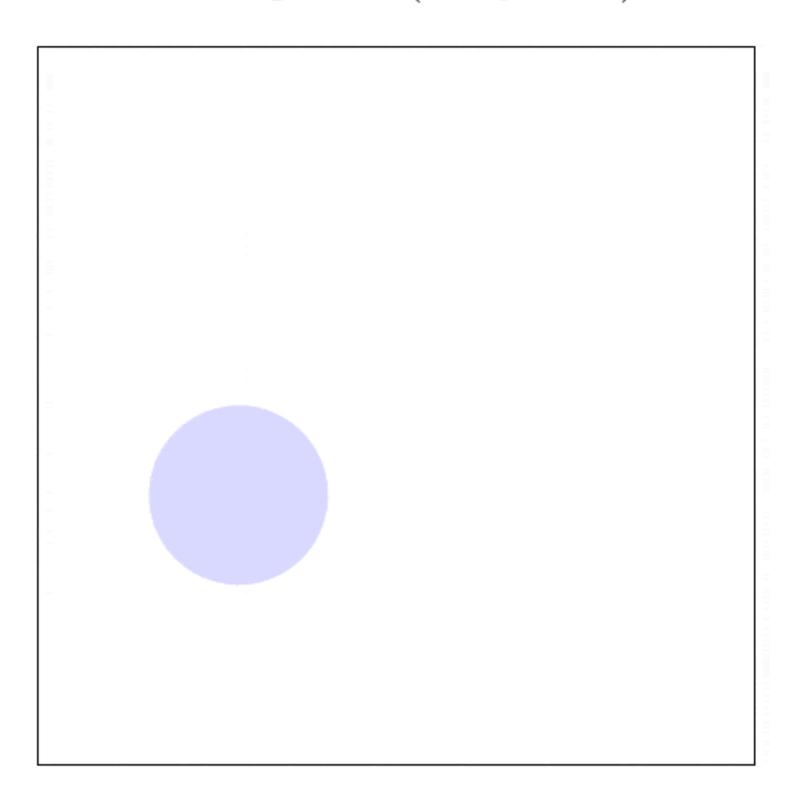
[Cokelaer: <u>0706.4437</u>]

[Owen: <u>9511032</u>]





0 templates (0 rejected)

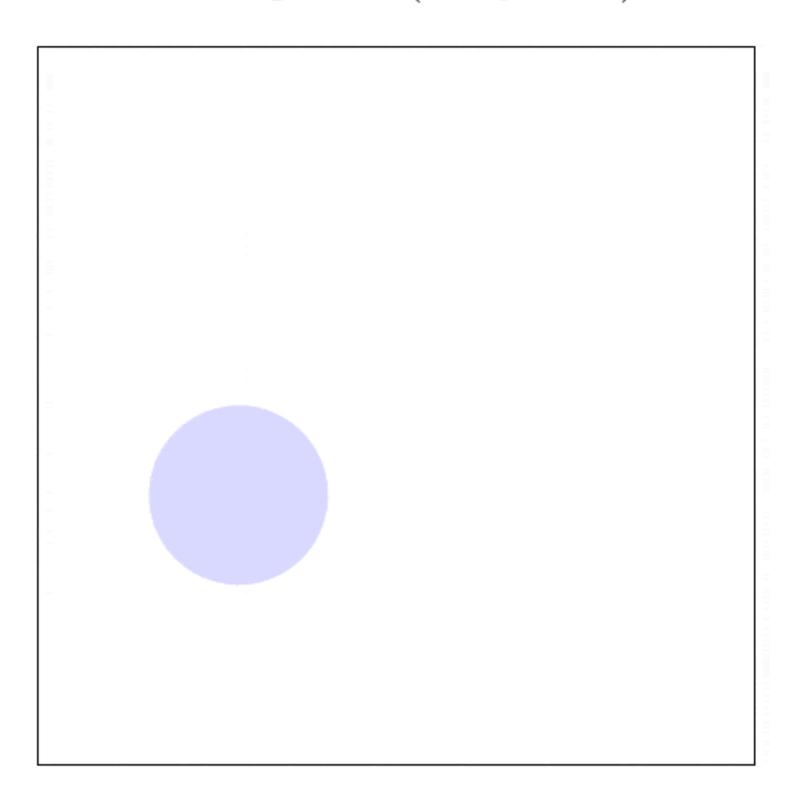


- Does not require a metric
- Can be very slow to converge





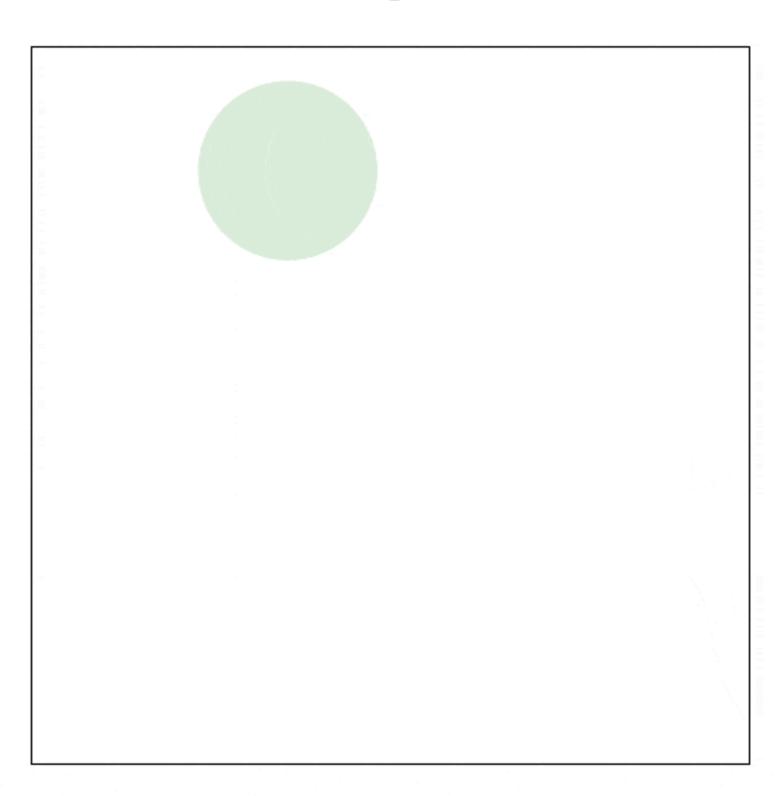
0 templates (0 rejected)



- Does not require a metric
- Can be very slow to converge





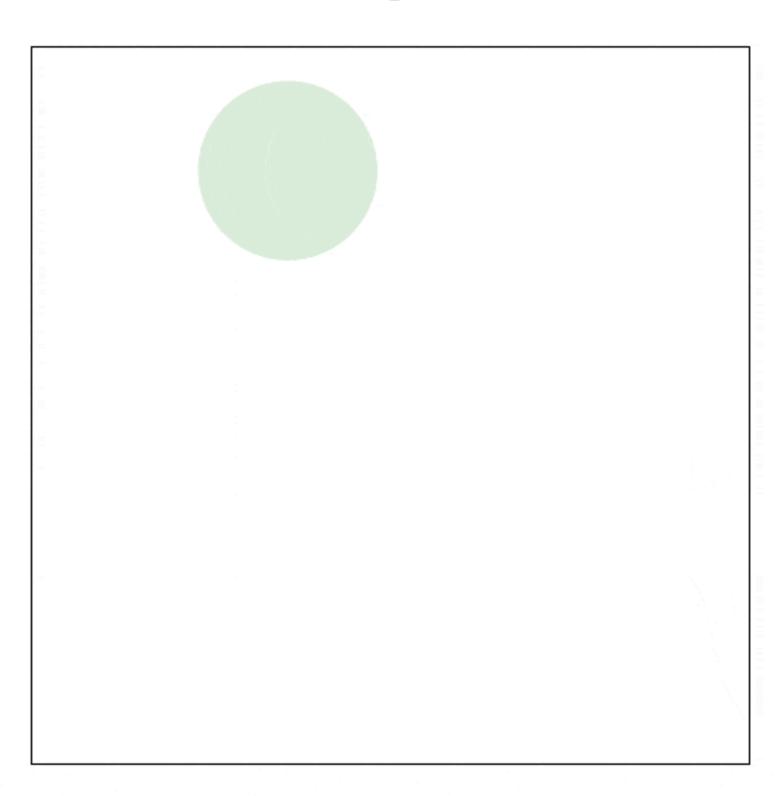


Random Placement:

- Quick to generate
- Over covers the parameter space (in low dimensions)
- Requires a metric







Random Placement:

- Quick to generate
- Over covers the parameter space (in low dimensions)
- Requires a metric

Backup

